



Practical Machine Learning

Lecture 8

Convolutional Neural Networks (CNN)

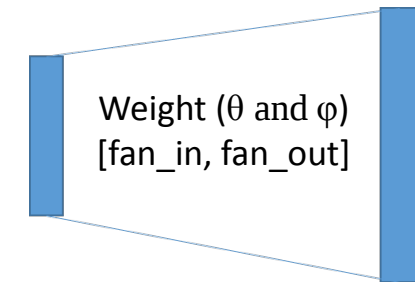
Dr. Suyong Eum



A question from the last class: initialization of parameters

- ❑ Xavier (2010): <http://proceedings.mlr.press/v9/glorot10a/glorot10a.pdf>
 - Either using an uniform distribution or a normal distribution
 - It is implemented in the current Tensorflow: `tf.contrib.layers.xavier_initializer()`

$$U\left(-\sqrt{\frac{6}{\text{fan_in} + \text{fan_out}}}, \sqrt{\frac{6}{\text{fan_in} + \text{fan_out}}}\right), N\left(0, \frac{2}{\text{fan_in} + \text{fan_out}}\right)$$



in_dimension
: fan_in

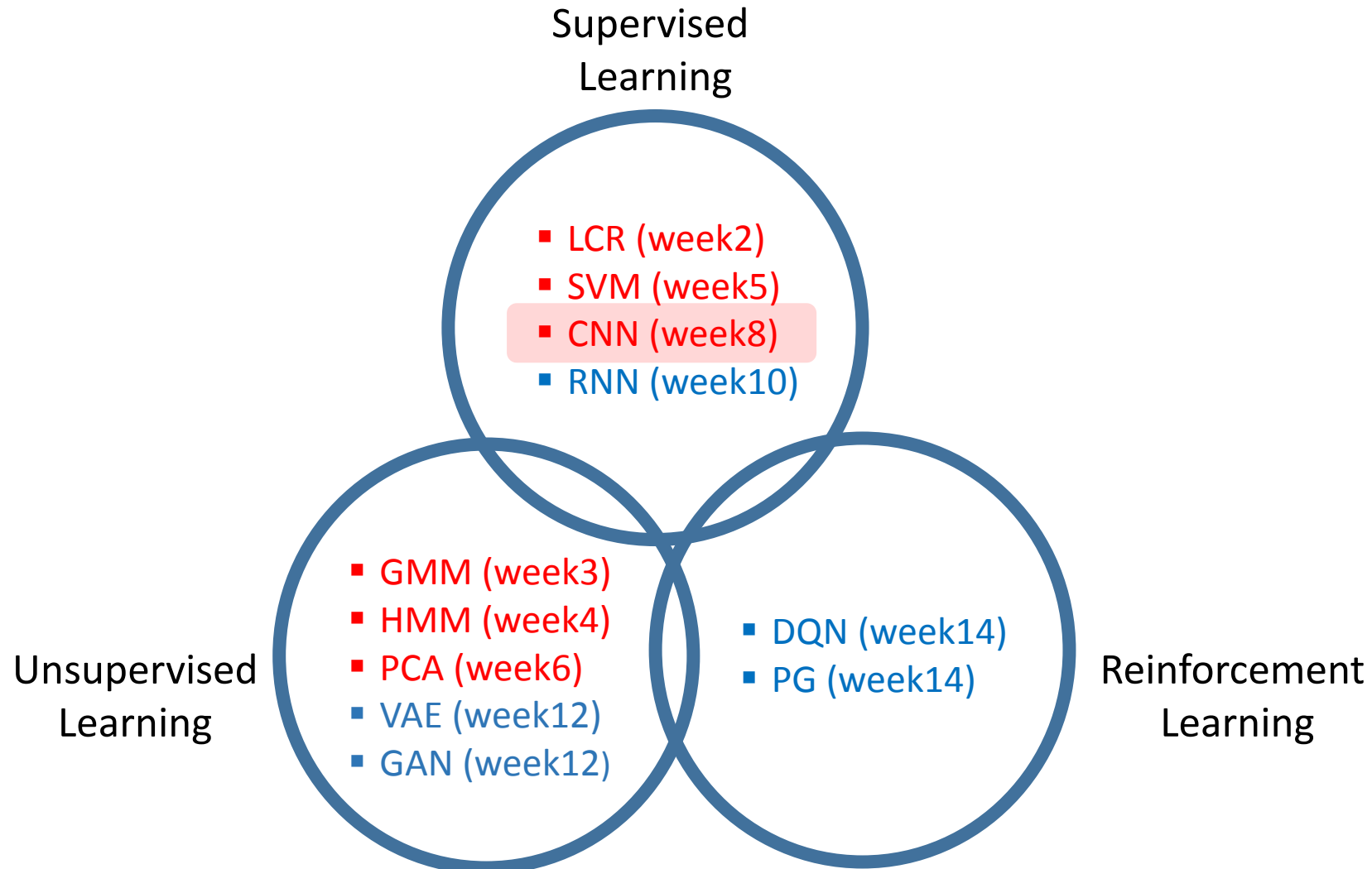
out_dimension
: fan_out

- ❑ He (2015): <https://arxiv.org/pdf/1502.01852.pdf>
 - Using a normal distribution

$$N\left(0, \frac{2}{\text{fan_in}}\right)$$

```
def xavier_init(size):  
    in_dim = size[0]  
    xavier_stddev = 1. / tf.sqrt(in_dim / 2.)  
    return tf.random_normal(shape=size, stddev=xavier_stddev)
```

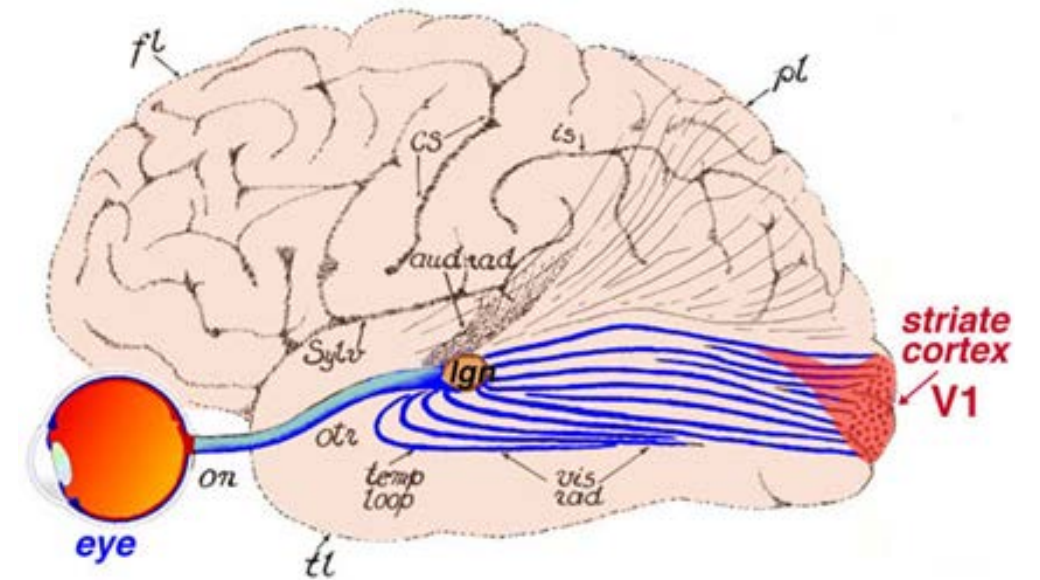
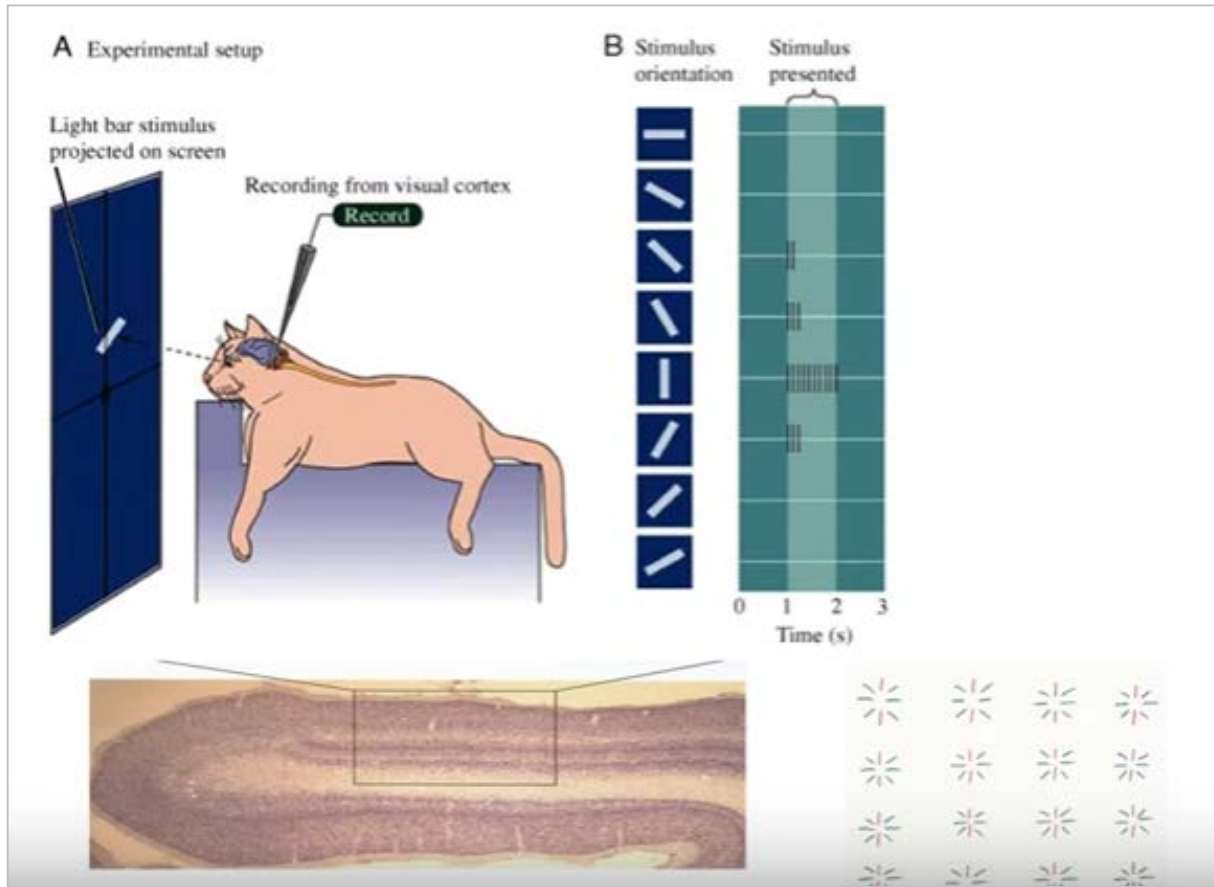
```
def xavier_init(fan_in, fan_out, constant=1):  
    low = -constant*np.sqrt(6.0/(fan_in + fan_out))  
    high = constant*np.sqrt(6.0/(fan_in + fan_out))  
    return tf.random_uniform((fan_in, fan_out),  
                             minval=low, maxval=high,  
                             dtype=tf.float32)
```



You are going to learn

- ❑ What a Convolutional Neural Network (CNN) is,
- ❑ How they work,
- ❑ How to train CNNs using backpropagation.

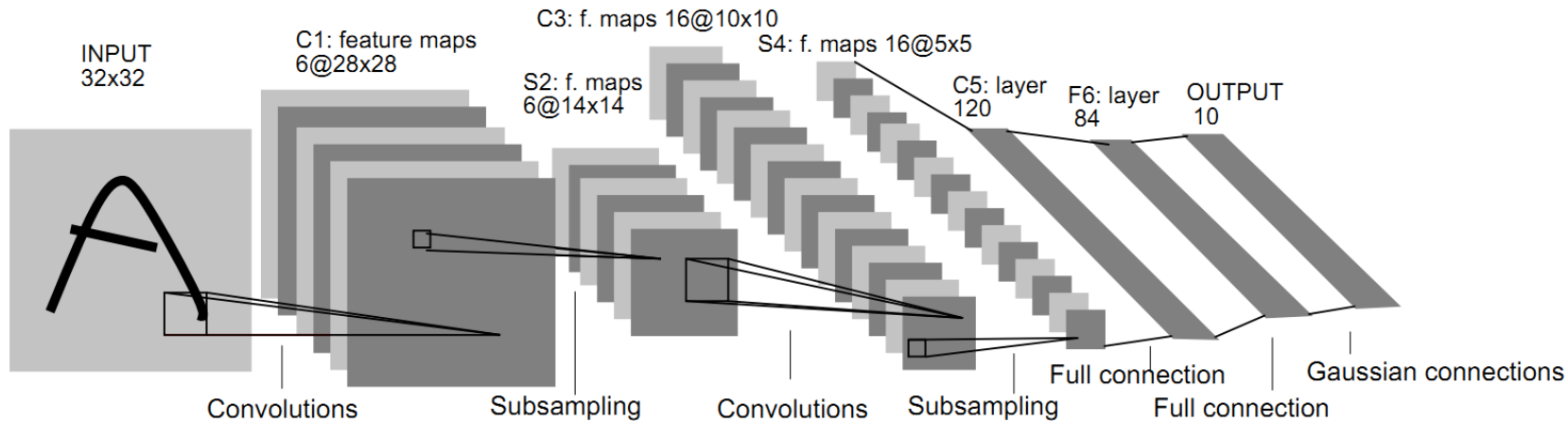
□ Hubel and Wiesel in 1962



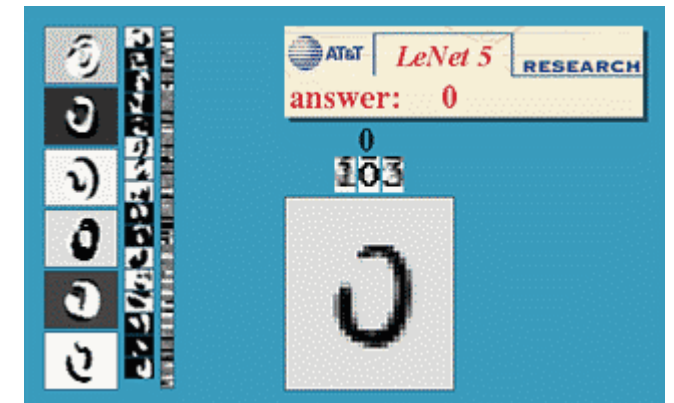
History of CNN – 1995

❑ LeCun et al, “Convolutional Networks for Images, Speech, and Time-Series”

- <http://yann.lecun.com/exdb/publis/pdf/lecun-bengio-95a.pdf>

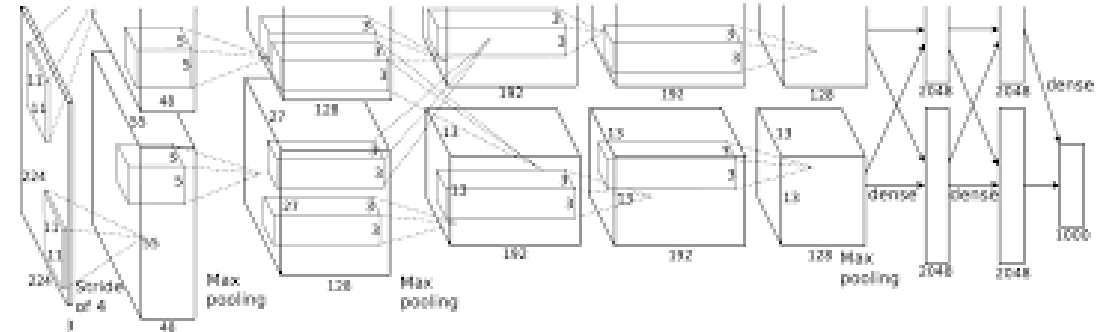
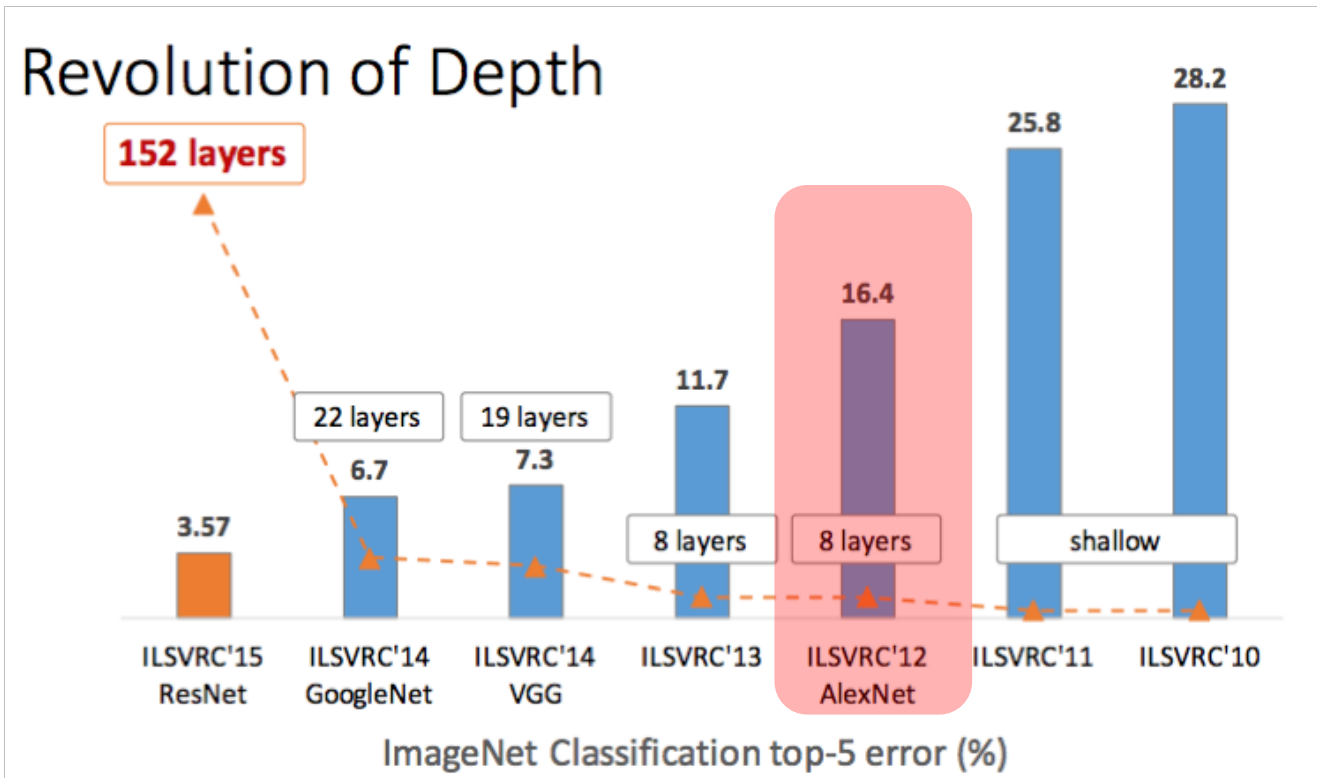


Lecun Yann
Director of AI Research, Facebook



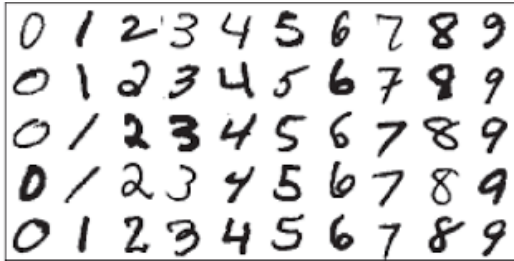
History of CNN – 2012

- ❑ Alex Krizhevsky et al, “*ImageNet Classification with Deep Convolutional Neural Networks*” (2012)
 - Win the imageNet competition: annual Olympics of computer vision with astounding results compared to previously existing approaches (26% to 15%).



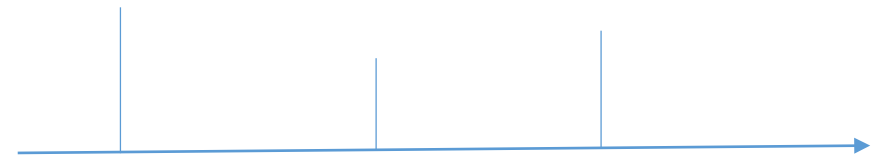
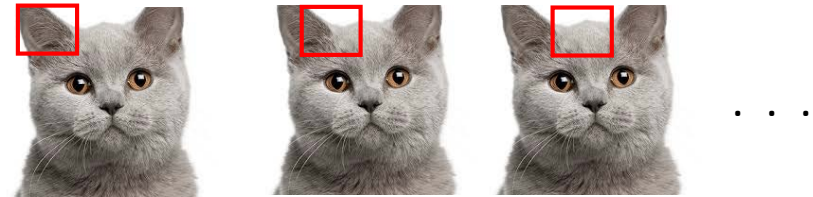
Why Convolutional Neural Networks (CNN)?

- ❑ Invariance to rotation, transformation, size, etc.



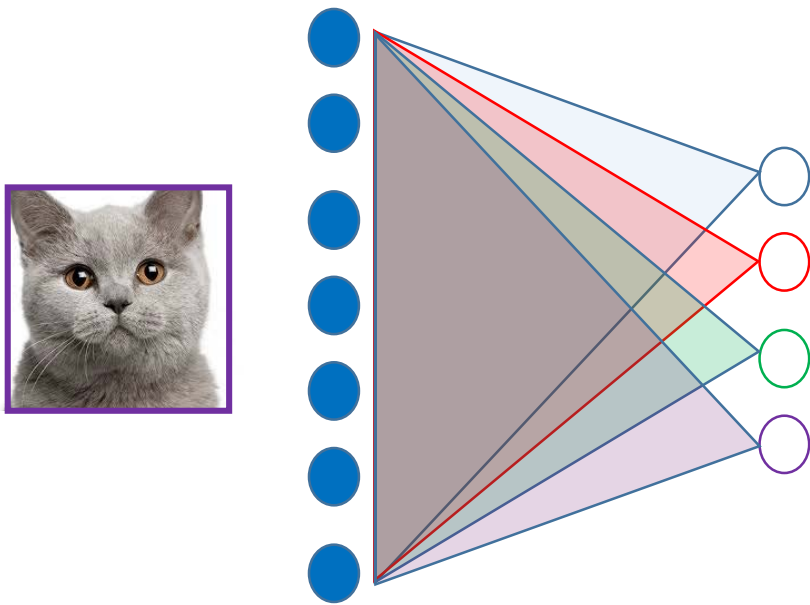
- ❑ Three architectural ideas of CNN

1. Local receptive fields
2. Weight sharing
3. Spatial or temporal subsampling



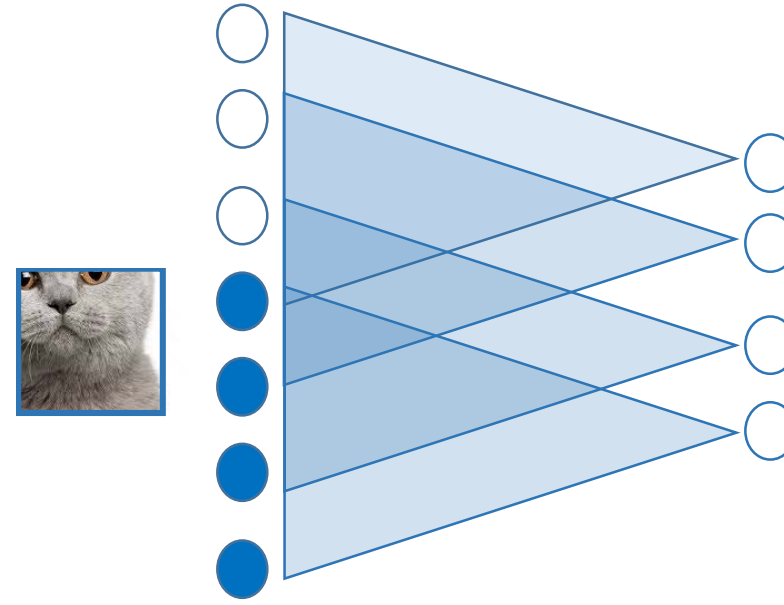
An idea of CNN

- ❑ A node takes responsibility for a portion of input data.



Fully connected Layer

- $4 \times 7 = 28$ weights

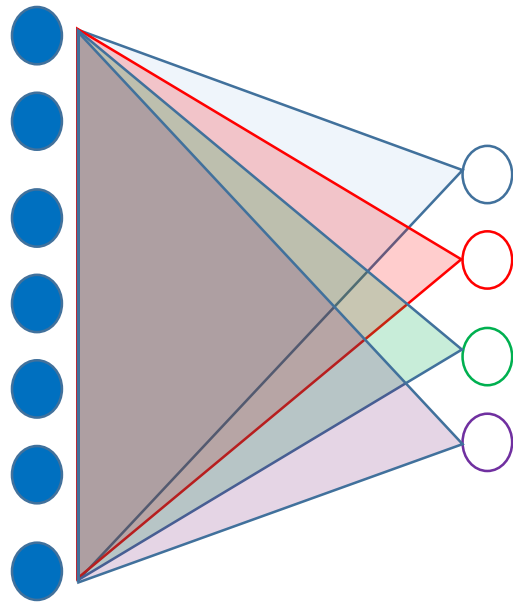


Convolutional Layer

- 4 weights

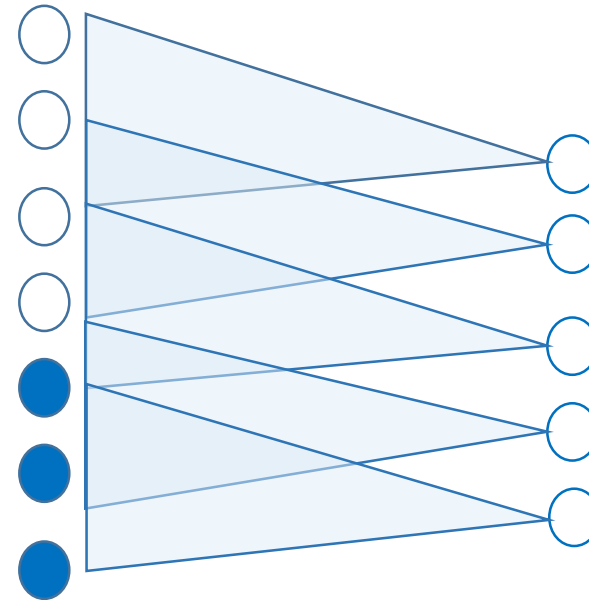
An idea of CNN

- ❑ A node takes responsibility for a portion of input data.



Fully connected Layer

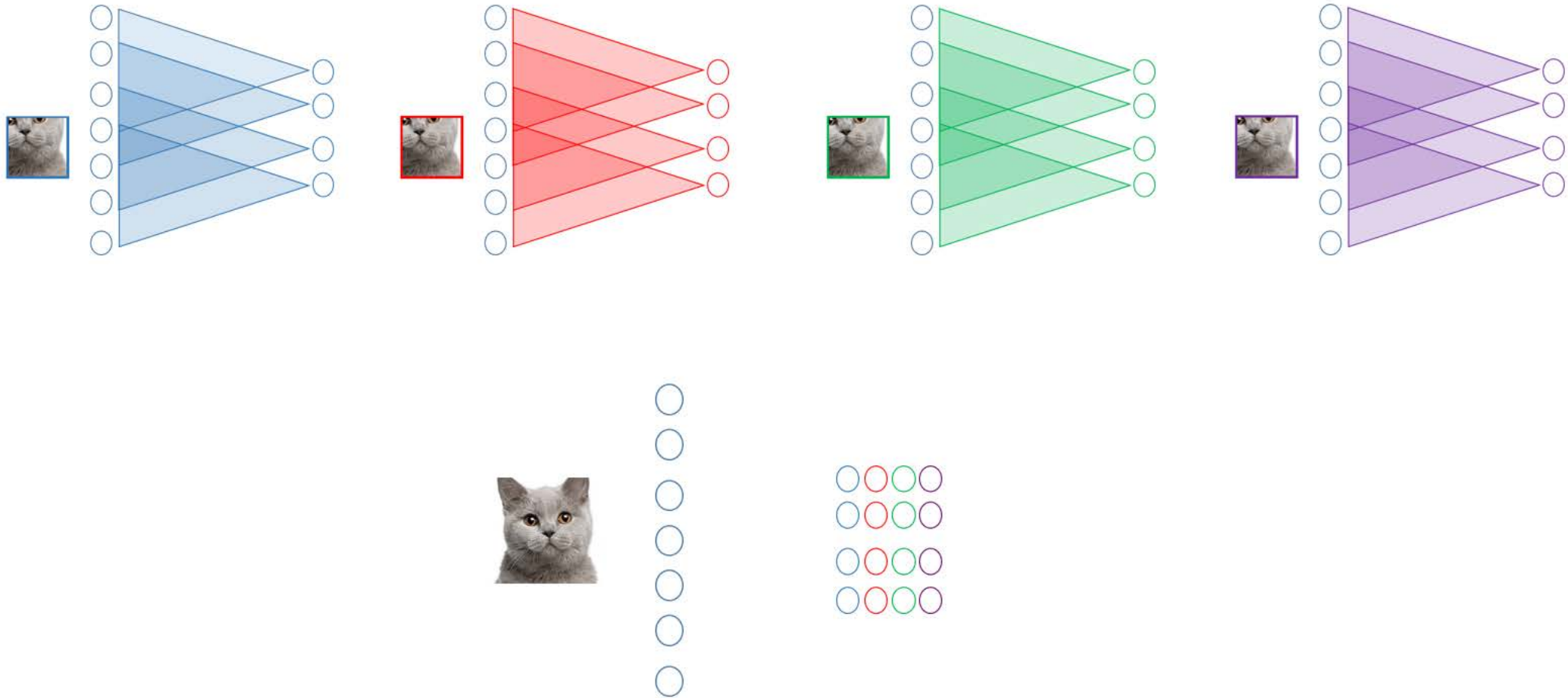
- $4 \times 7 = 28$ weights



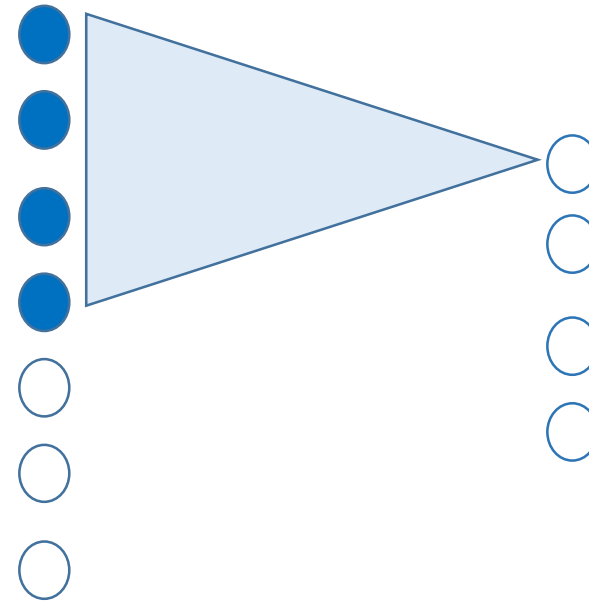
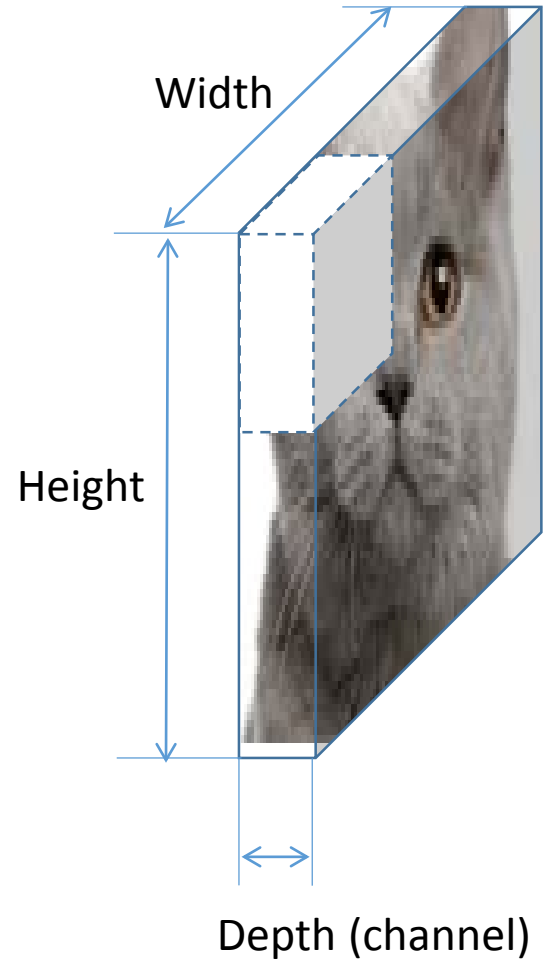
Convolutional Layer

- 3 weights

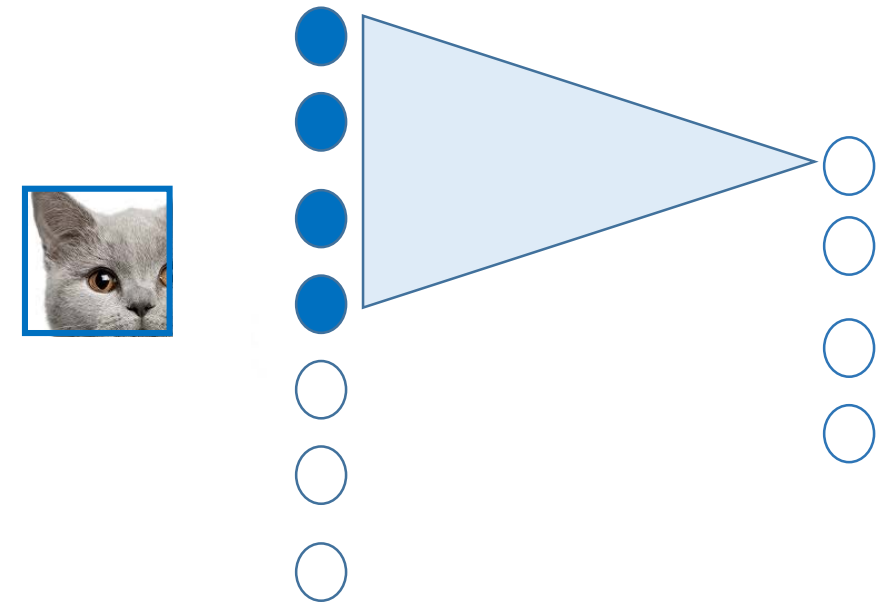
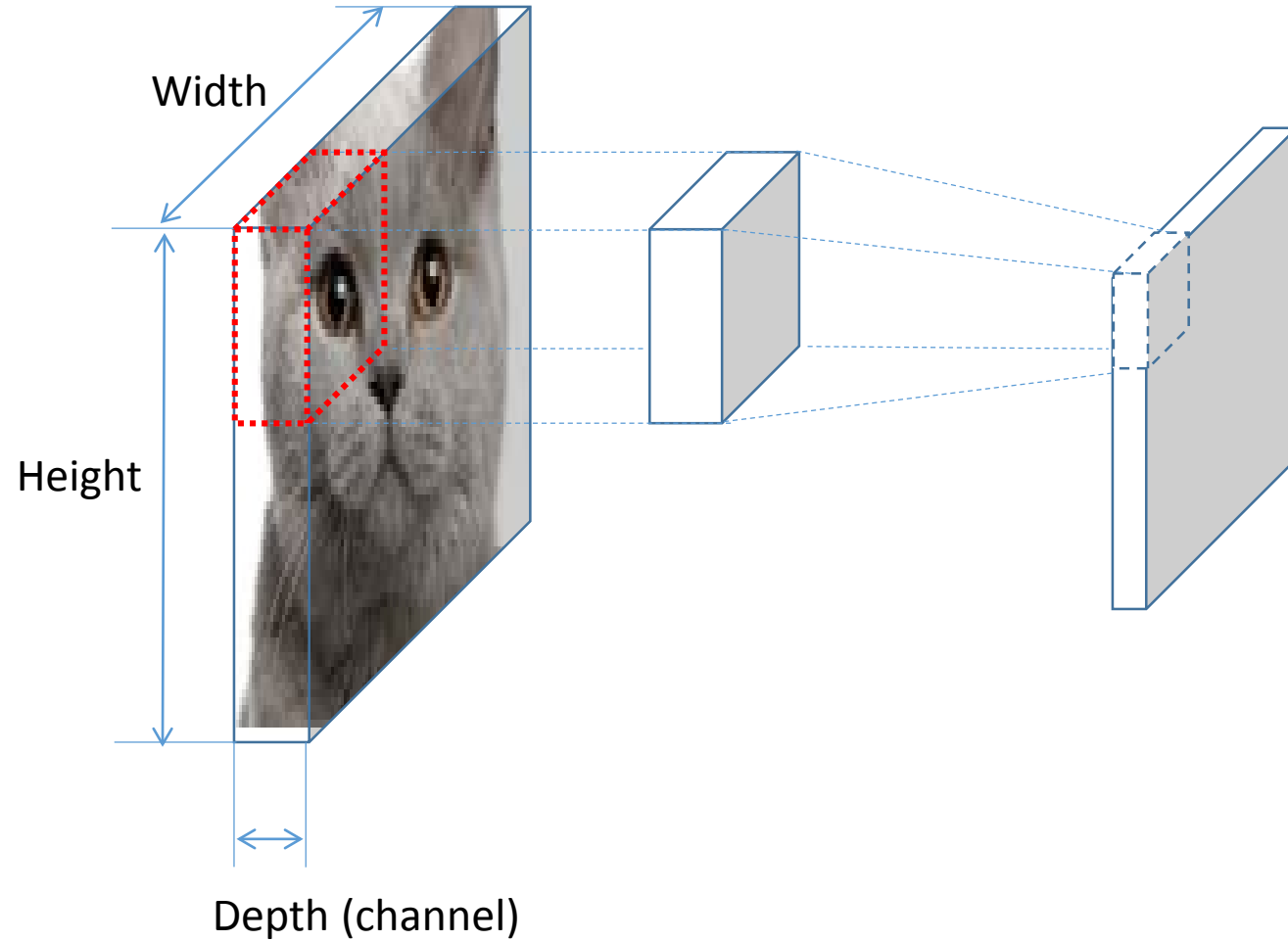
Convolution Layer tends to produce multiple results



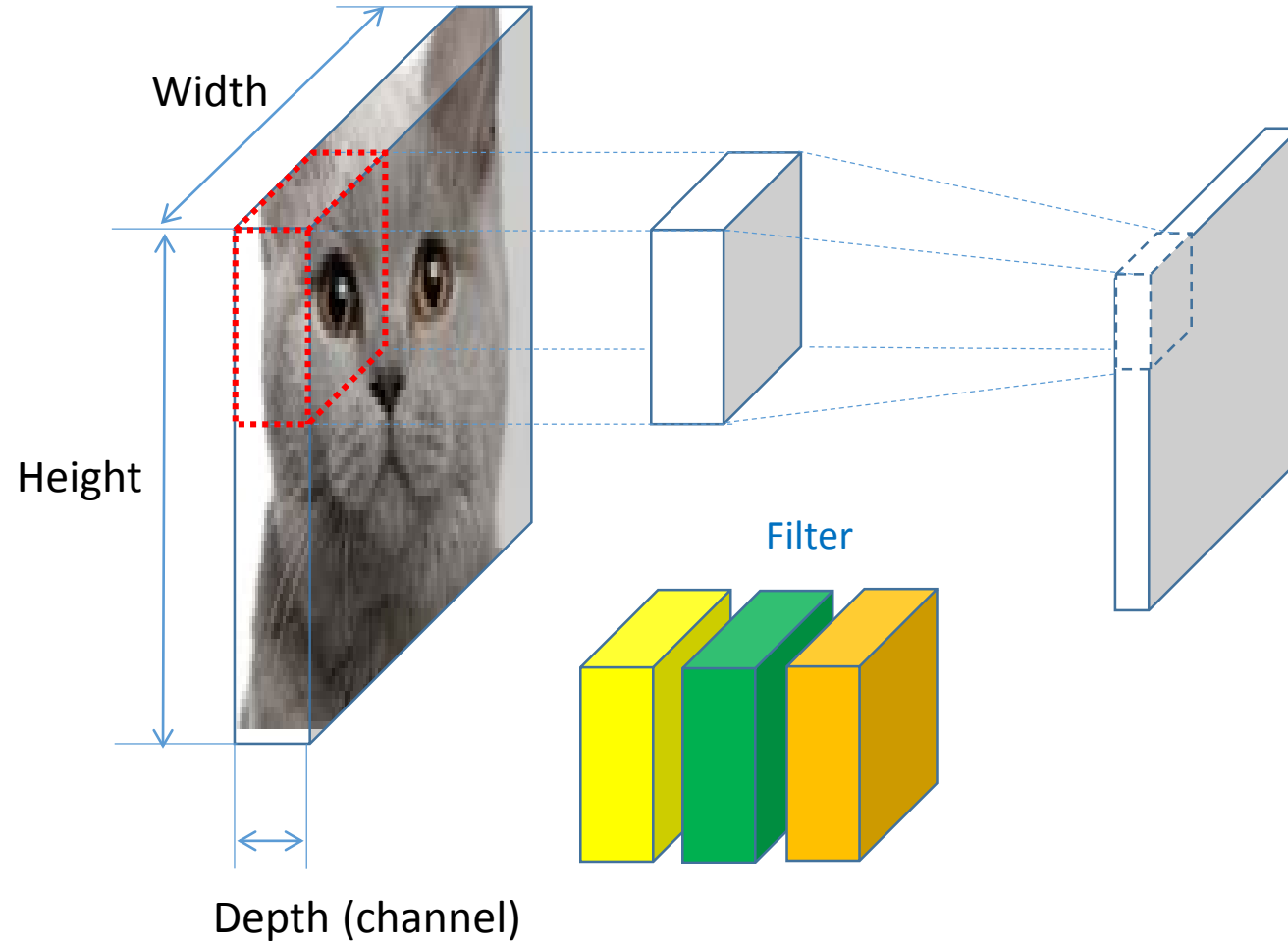
2-D representation vs 1-D representation



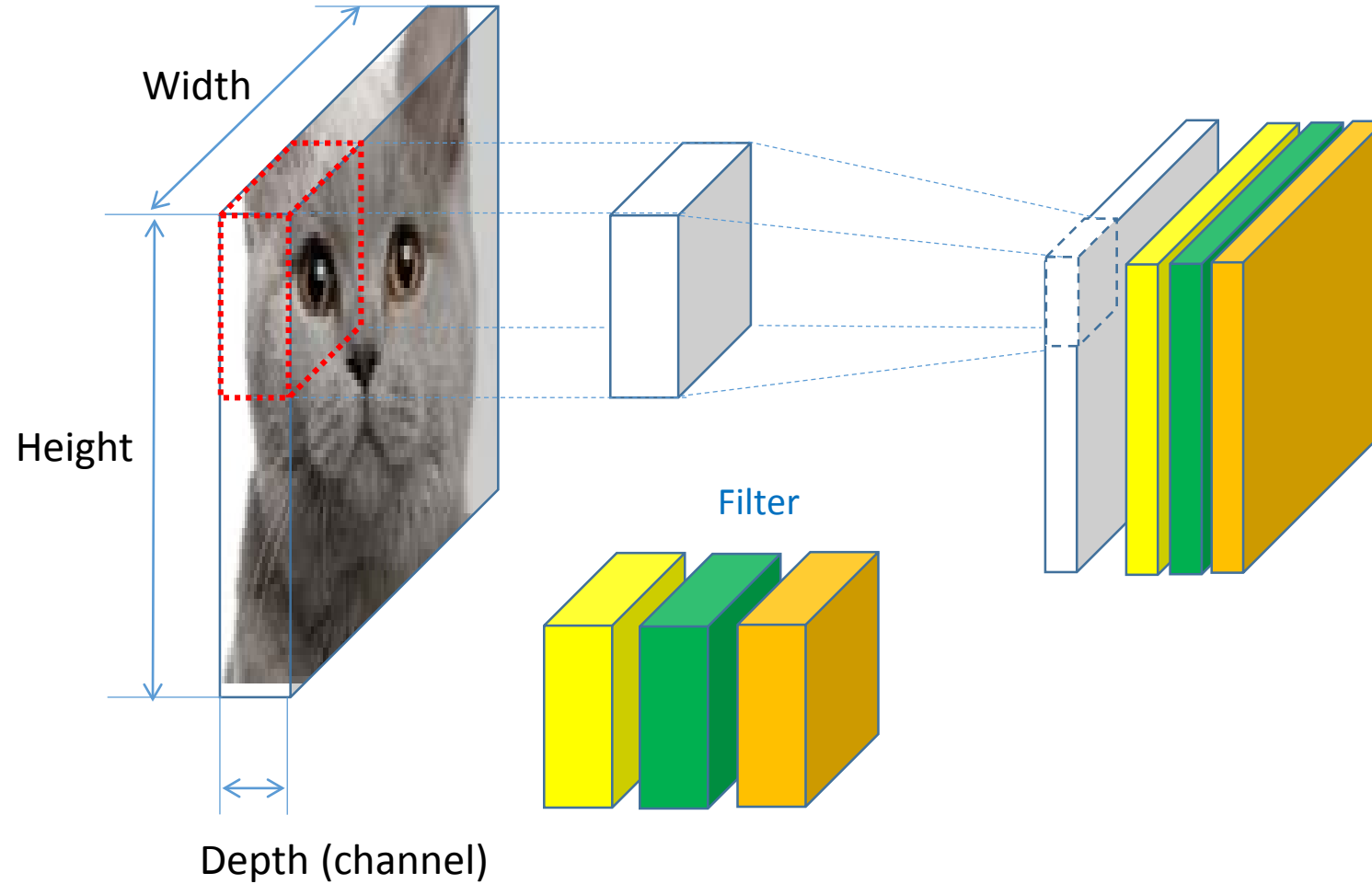
2-D representation vs 1-D representation



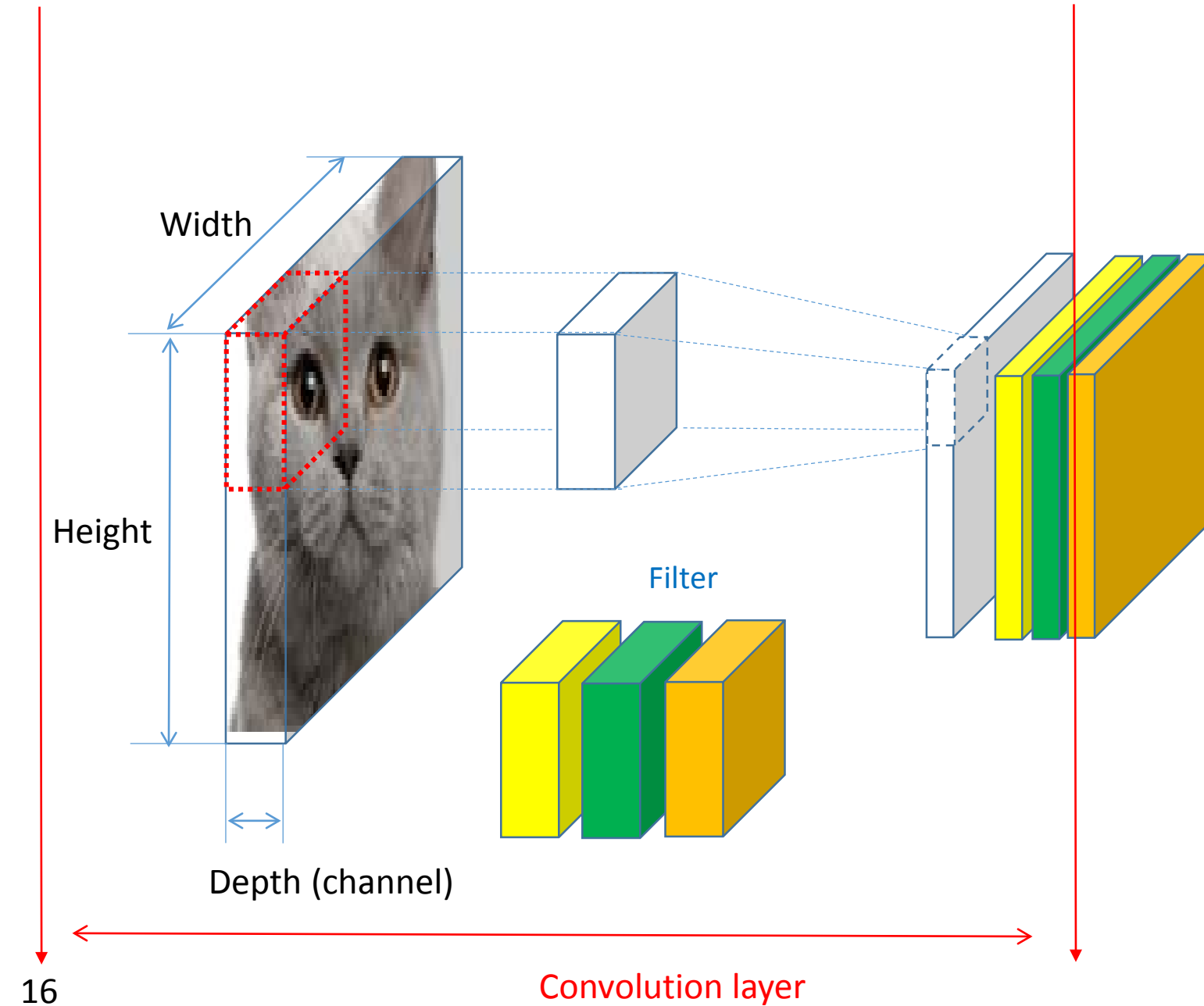
2-D representation of CNN: How does it work?



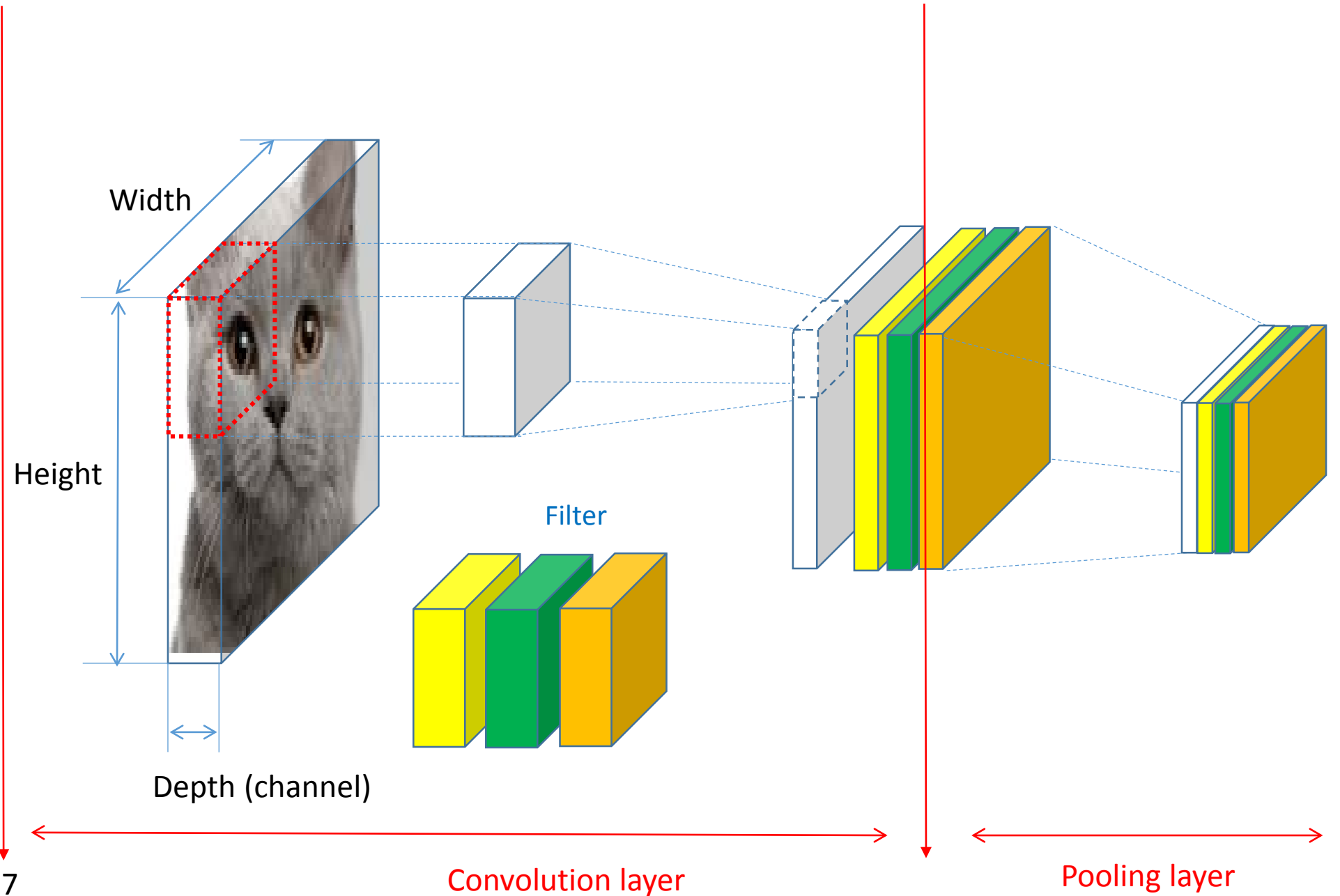
2-D representation of CNN: How does it work?



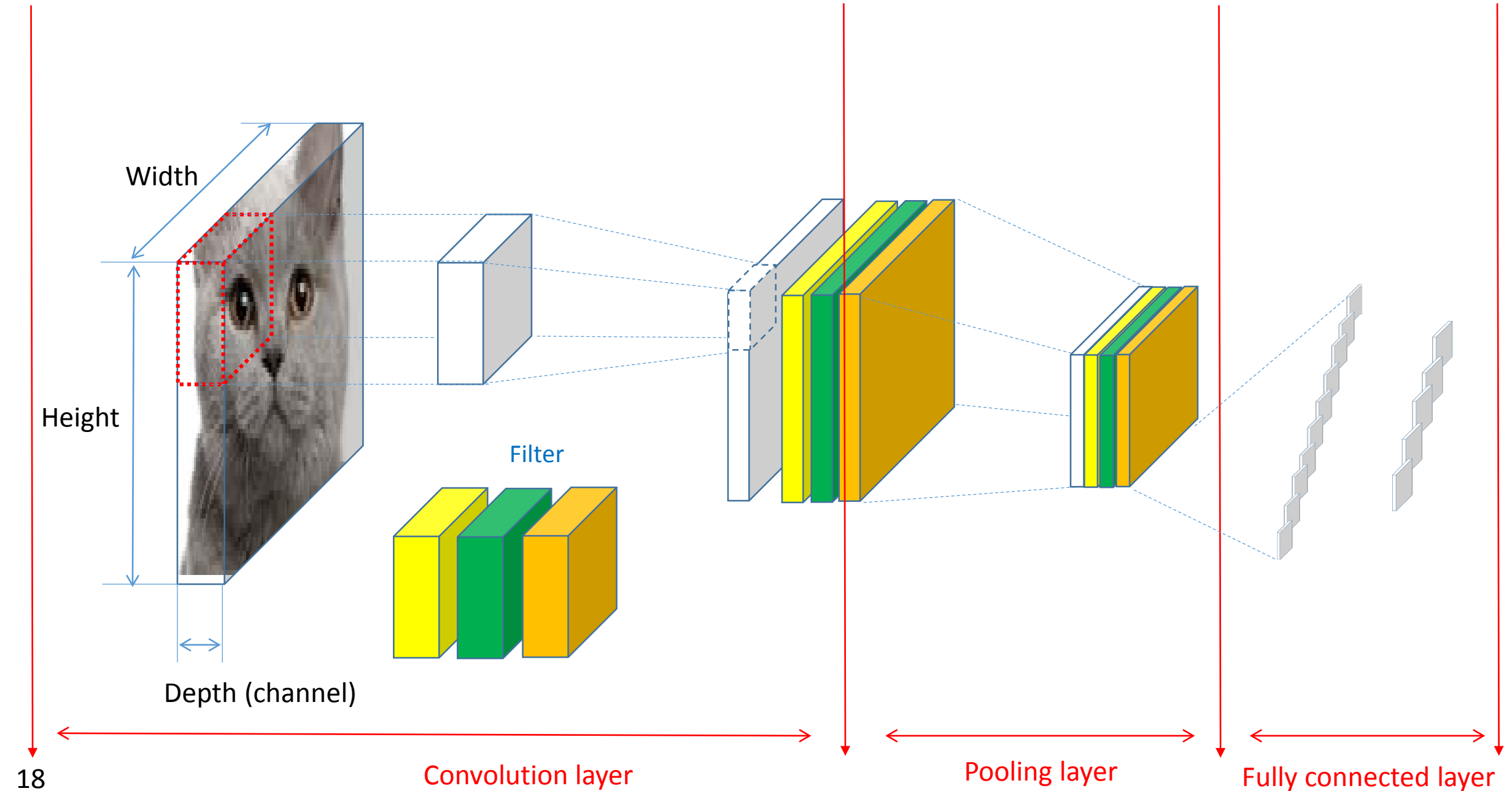
2-D representation of CNN: How does it work?



2-D representation of CNN: How does it work?

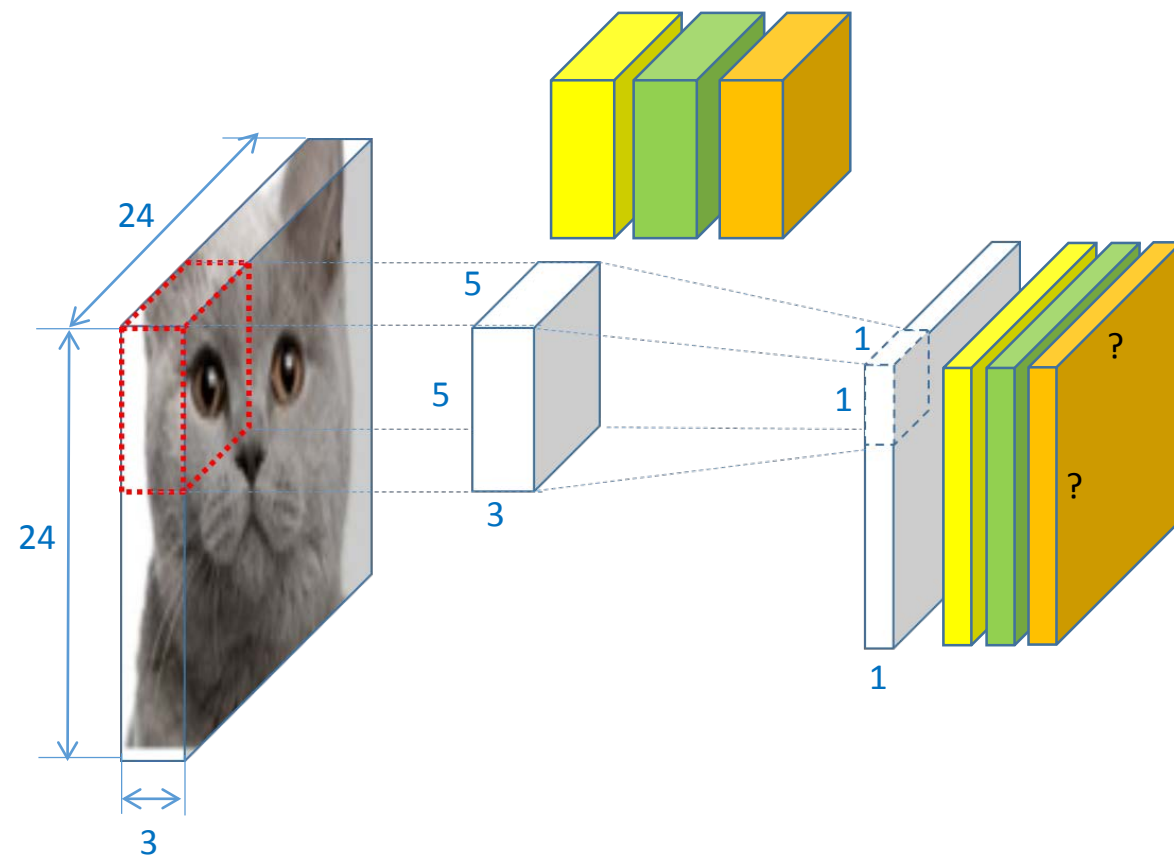


2-D representation of CNN: How does it work?



Convolution Layer

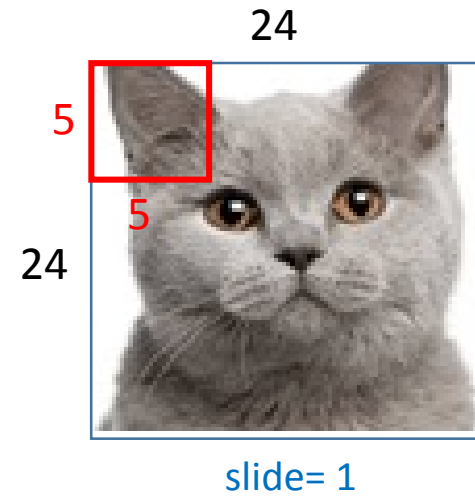
Convolutional Layer



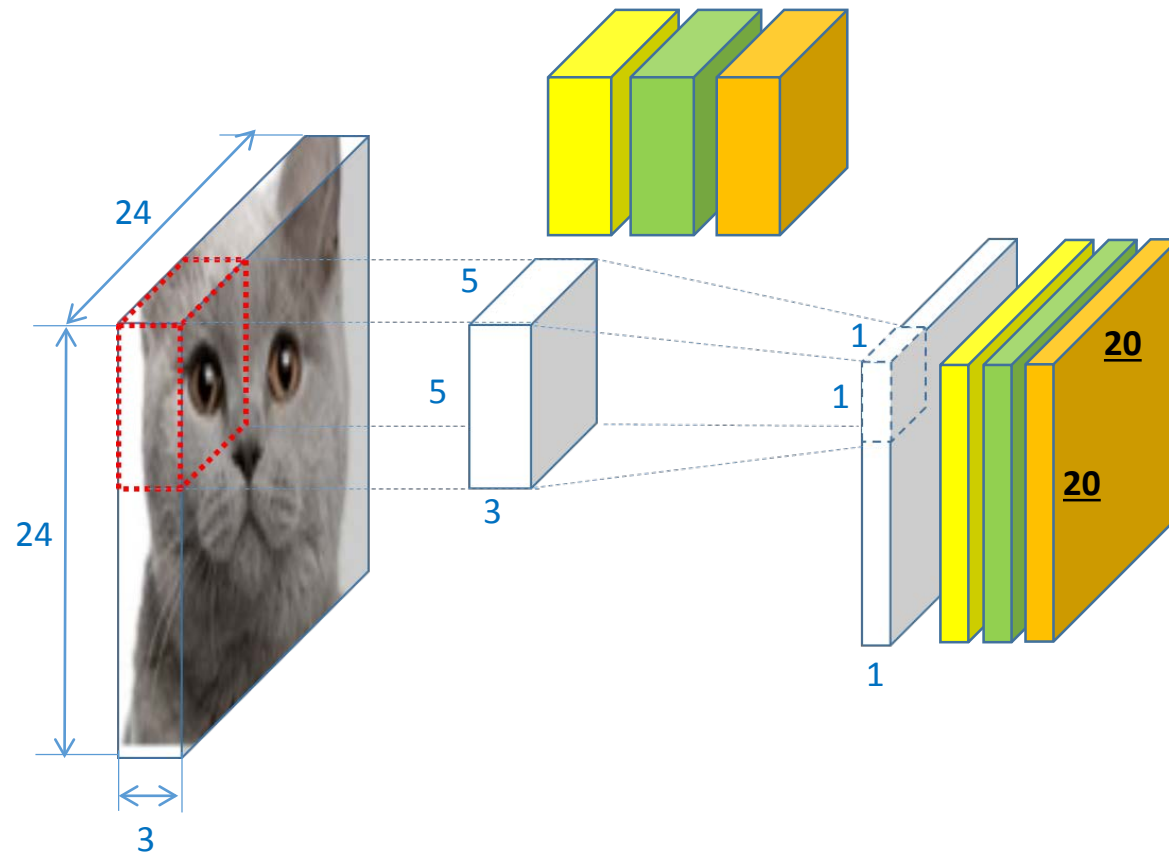
Input layer

Filters
Kernels

Activation maps
Feature maps



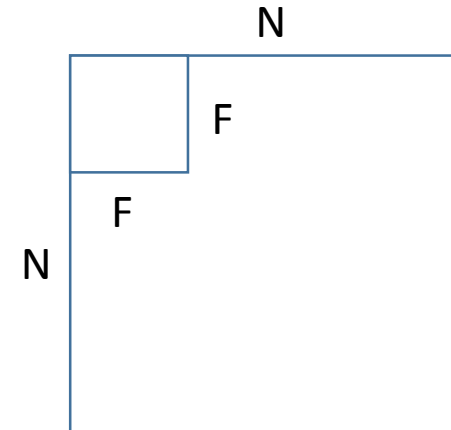
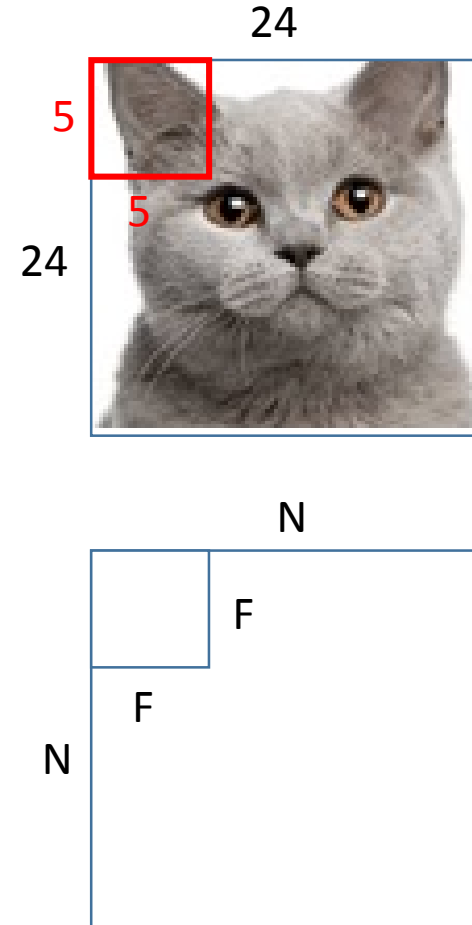
Convolutional Layer



Input layer

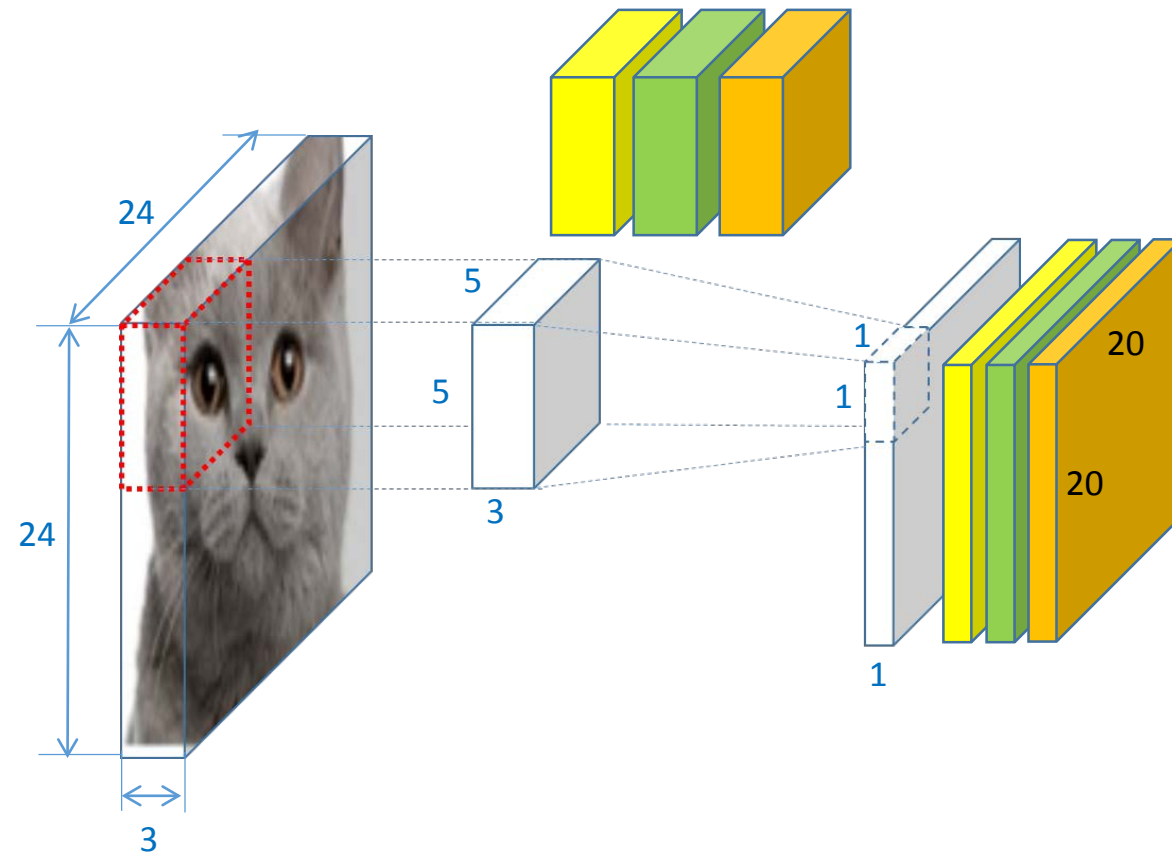
Filters
Kernels

Activation maps
Feature maps



$$\text{Size of activation map} = \frac{(N - F)}{\text{stride}} + 1$$

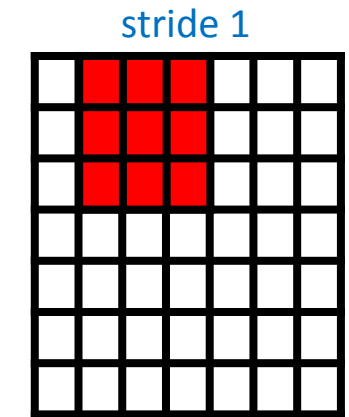
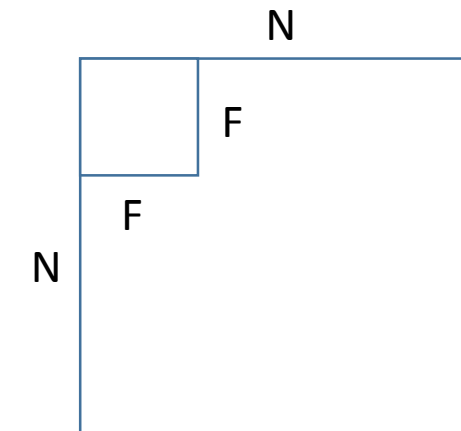
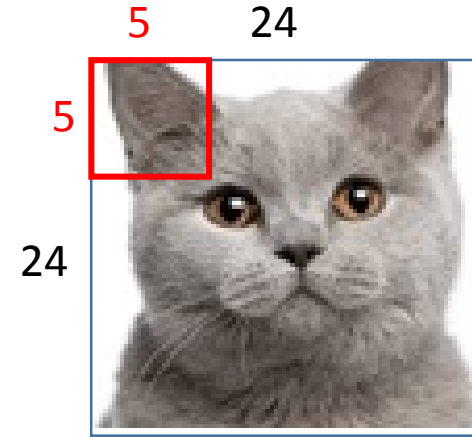
Convolutional Layer



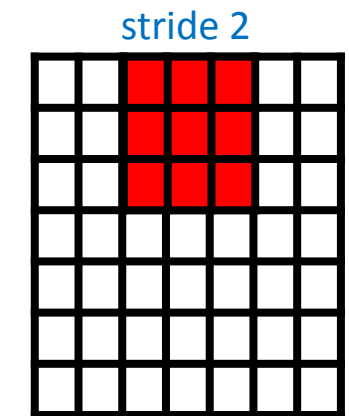
Input layer

Filters
Kernels

Activation maps
Feature maps



Activation map
(5 x 5 matrix)



Activation map
(3 x 3 matrix)

$$\text{Size of activation map} = \frac{(N - F)}{\text{stride}} + 1$$

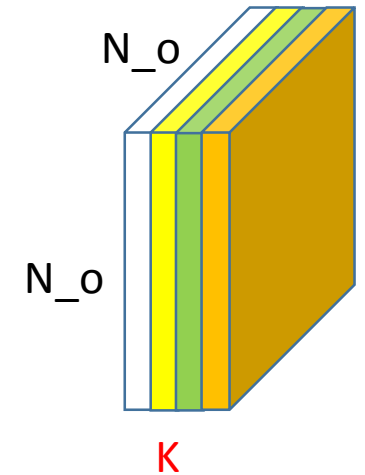
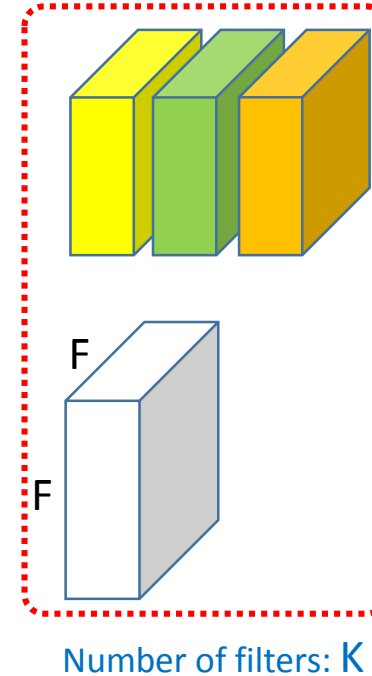
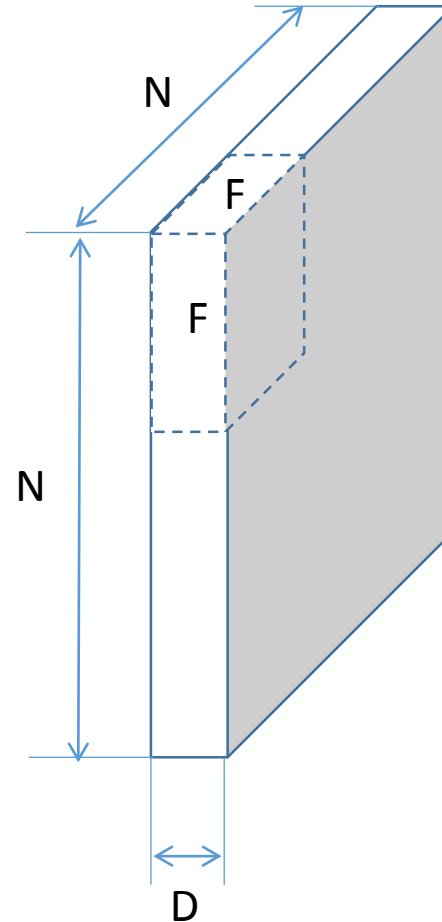
Convolutional Layer

Hyper parameters	Symbols
Number of filters	K
Size of the filter	F
Stride	S
Padding	P

0					0	0	0	0	0
0									0
0									0
0									0
0									0
0									0
0									0
0									0
0									0
0	0	0	0	0	0	0	0	0	0

- Padding: P=1
- Stride: S=1
- activation map becomes is 7 x 7 matrix

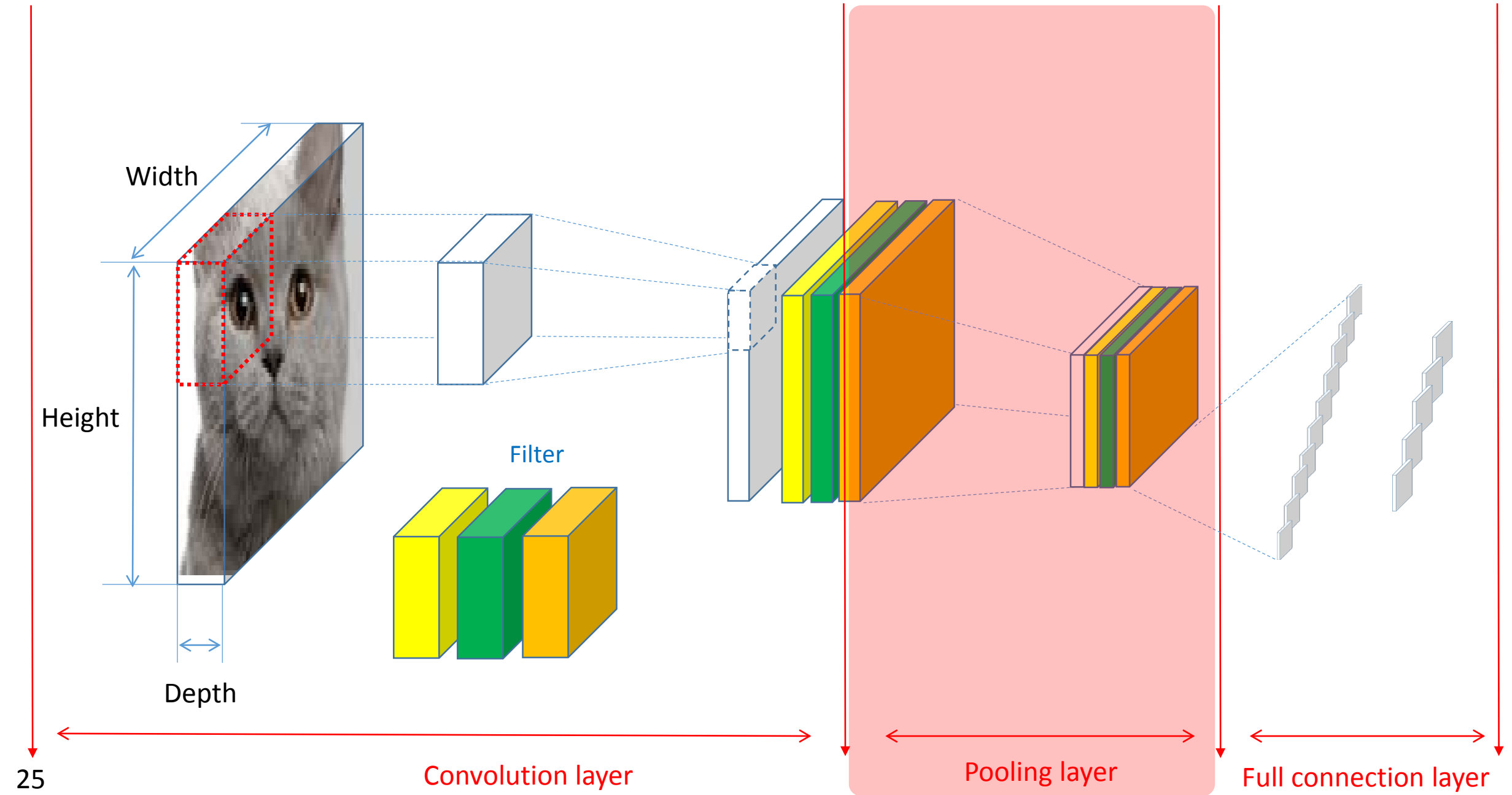
- Padding aims to maintain the original dimension of the original data.



$$N_o = \frac{(N - F + 2P)}{S} + 1$$

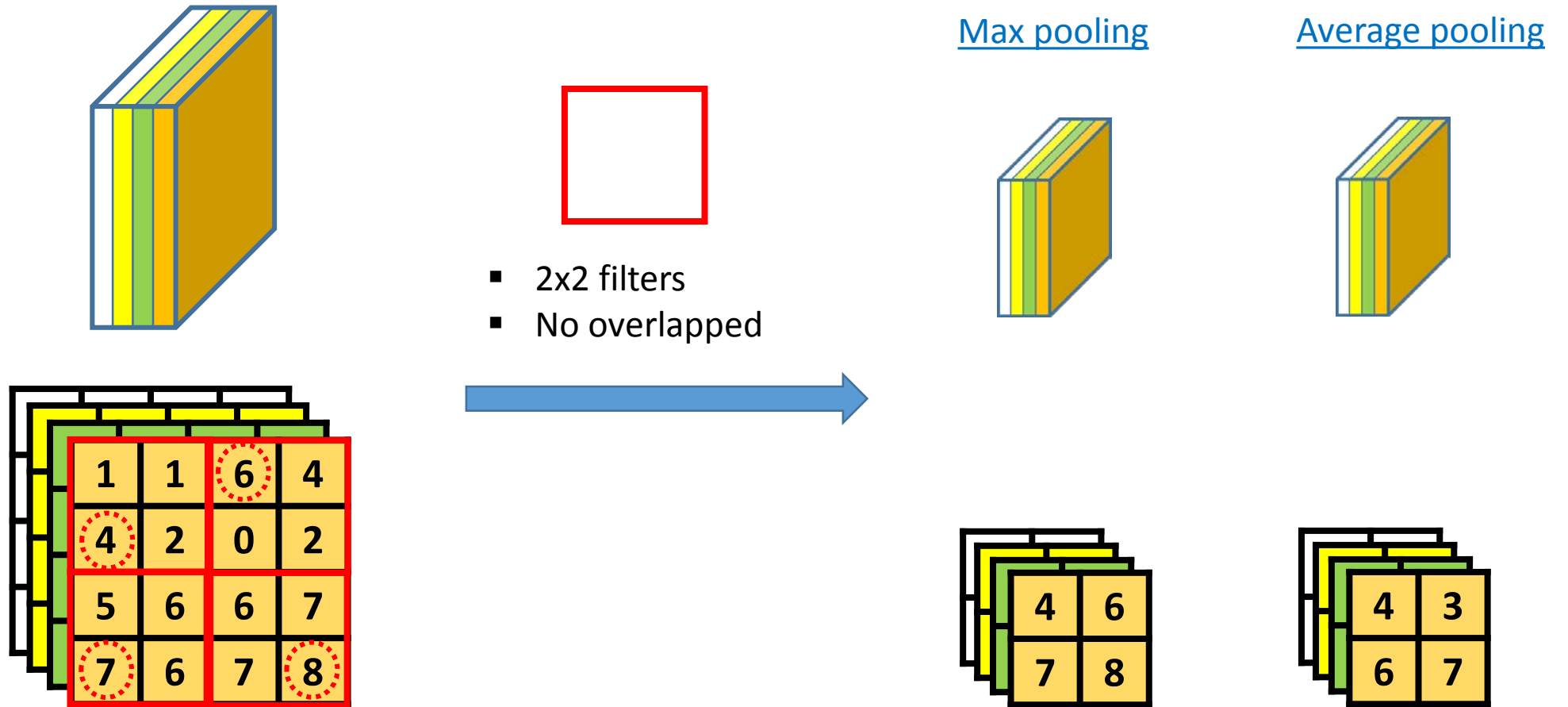
Pooling Layer

2-D representation of CNN: How does it work?



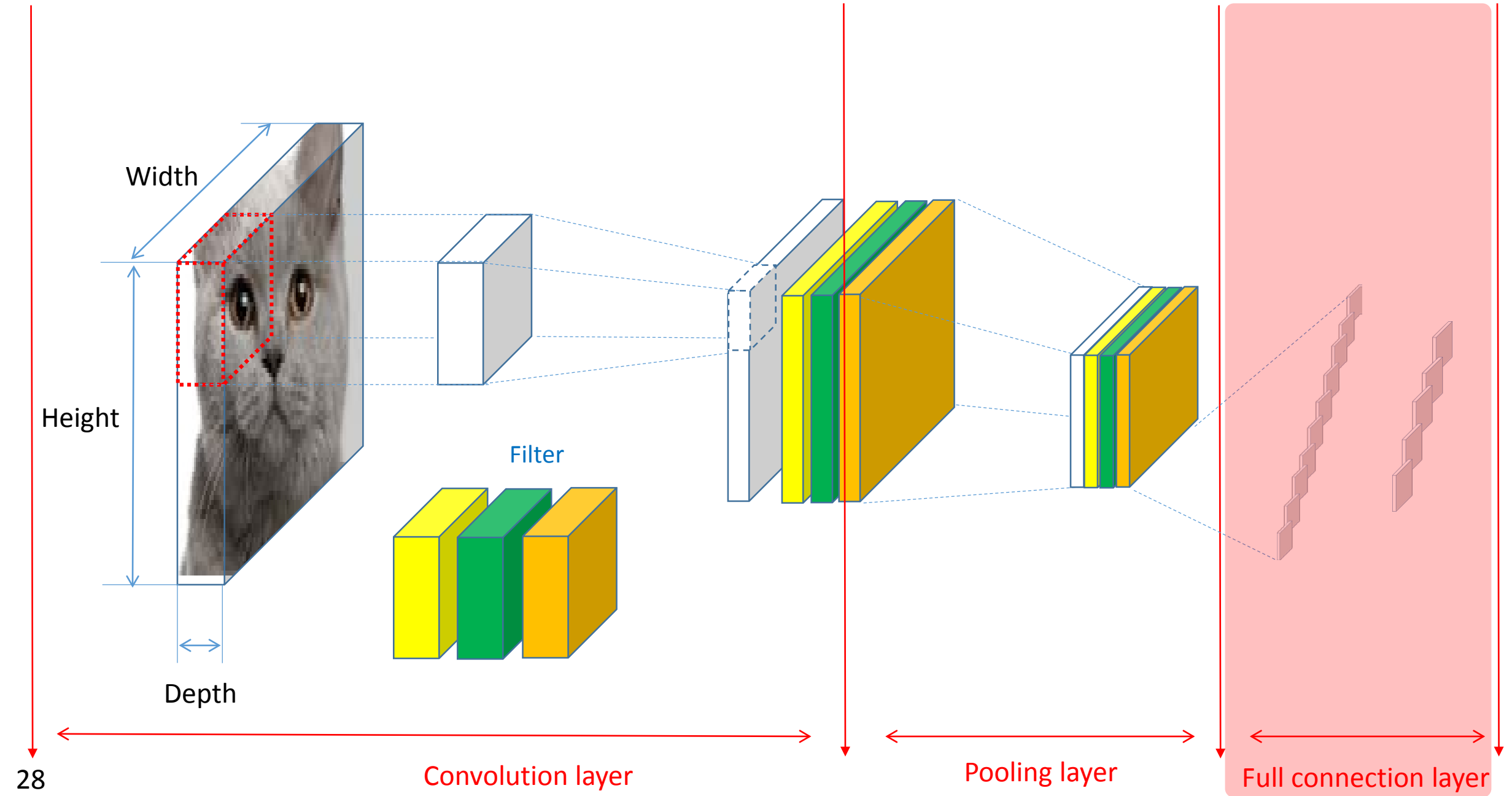
Pooling Layer

- ❑ This layer aims to reduce the dimension of each activation map.

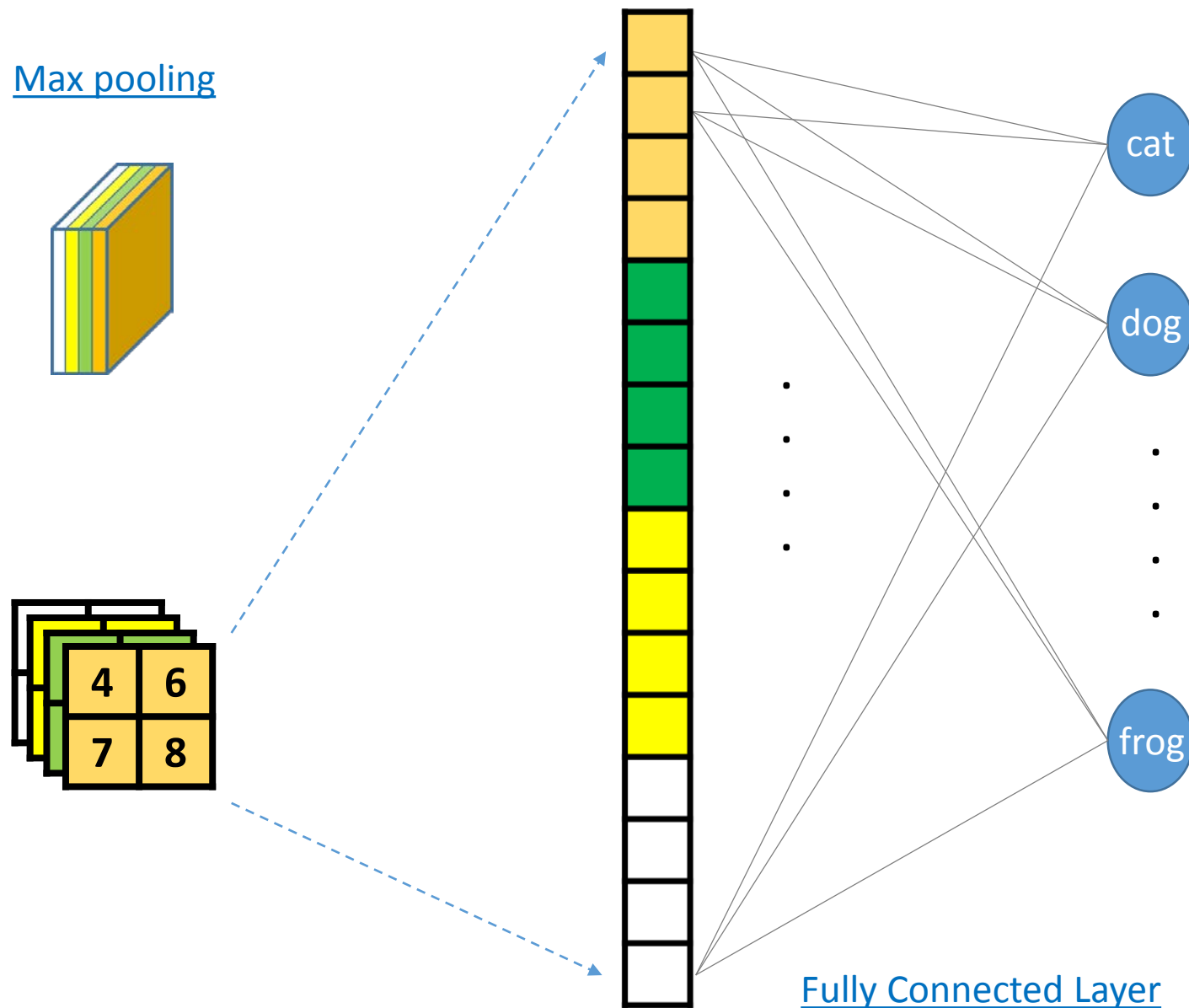


Fully Connected Layer

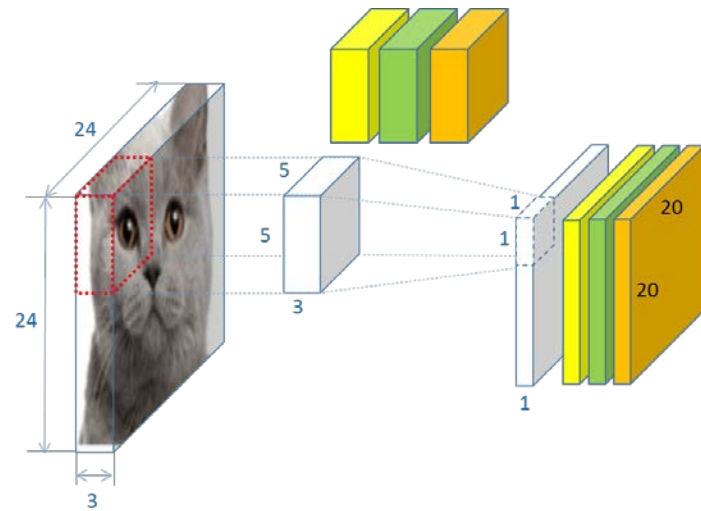
2-D representation of CNN: How does it work?



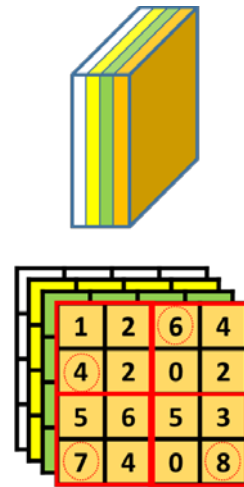
Fully Connected Layer



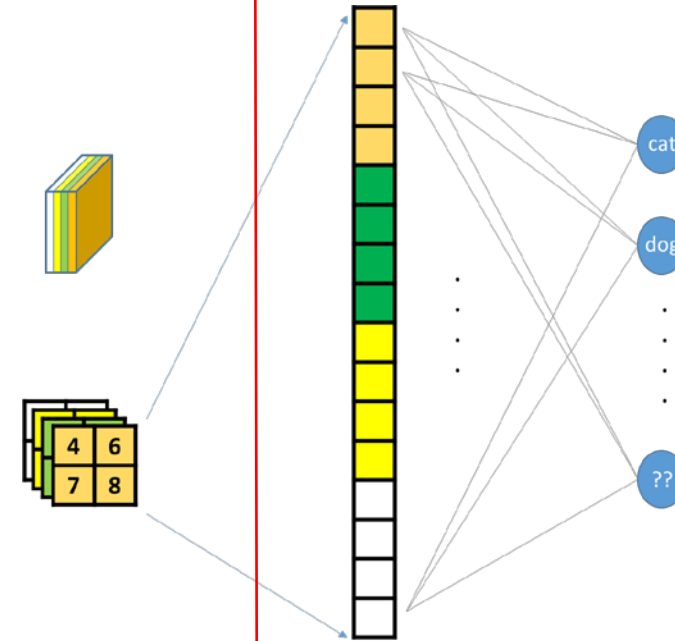
Summary



Convolution layer



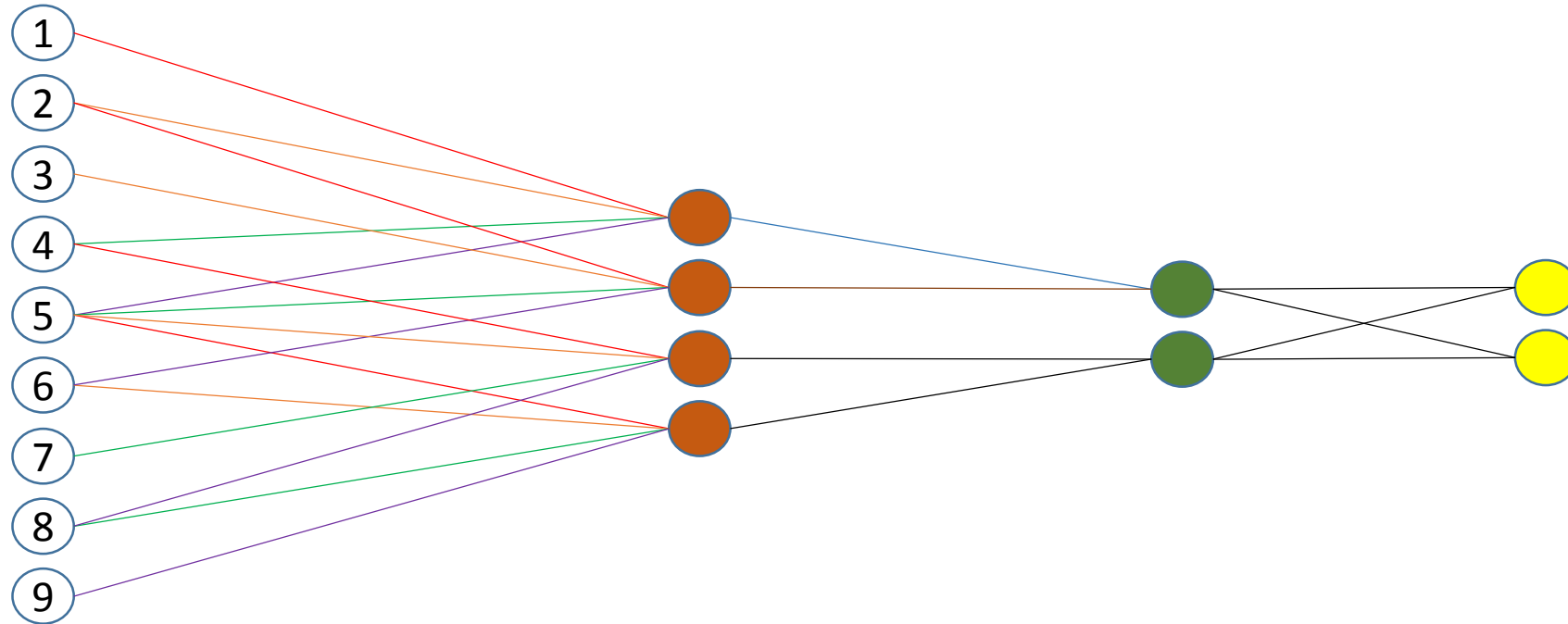
Pooling layer



Full connection layer

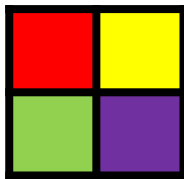
Backpropagation

Backpropagation



1	2	3
4	5	6
7	8	9

Input



Filter



Activation map



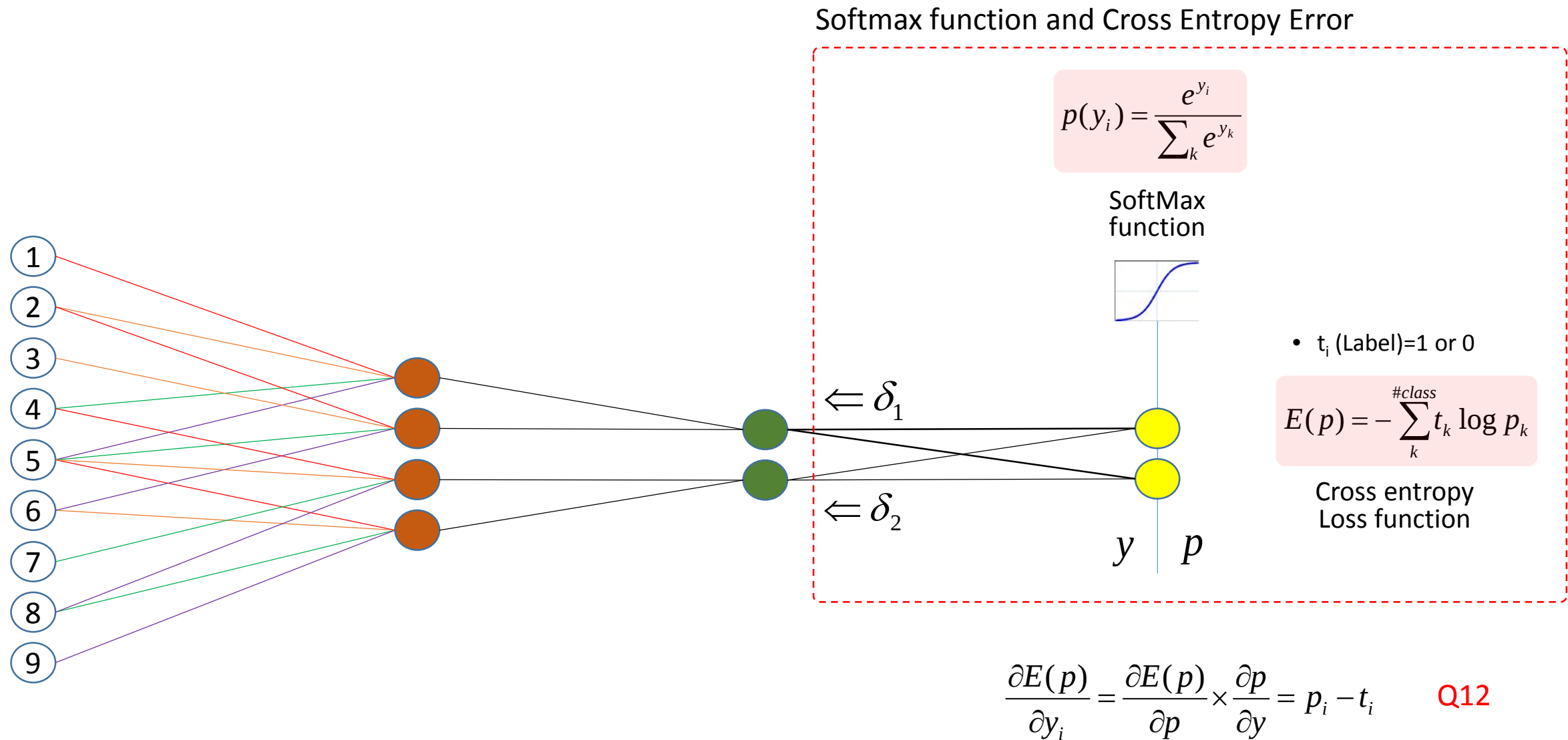
Max
Filter



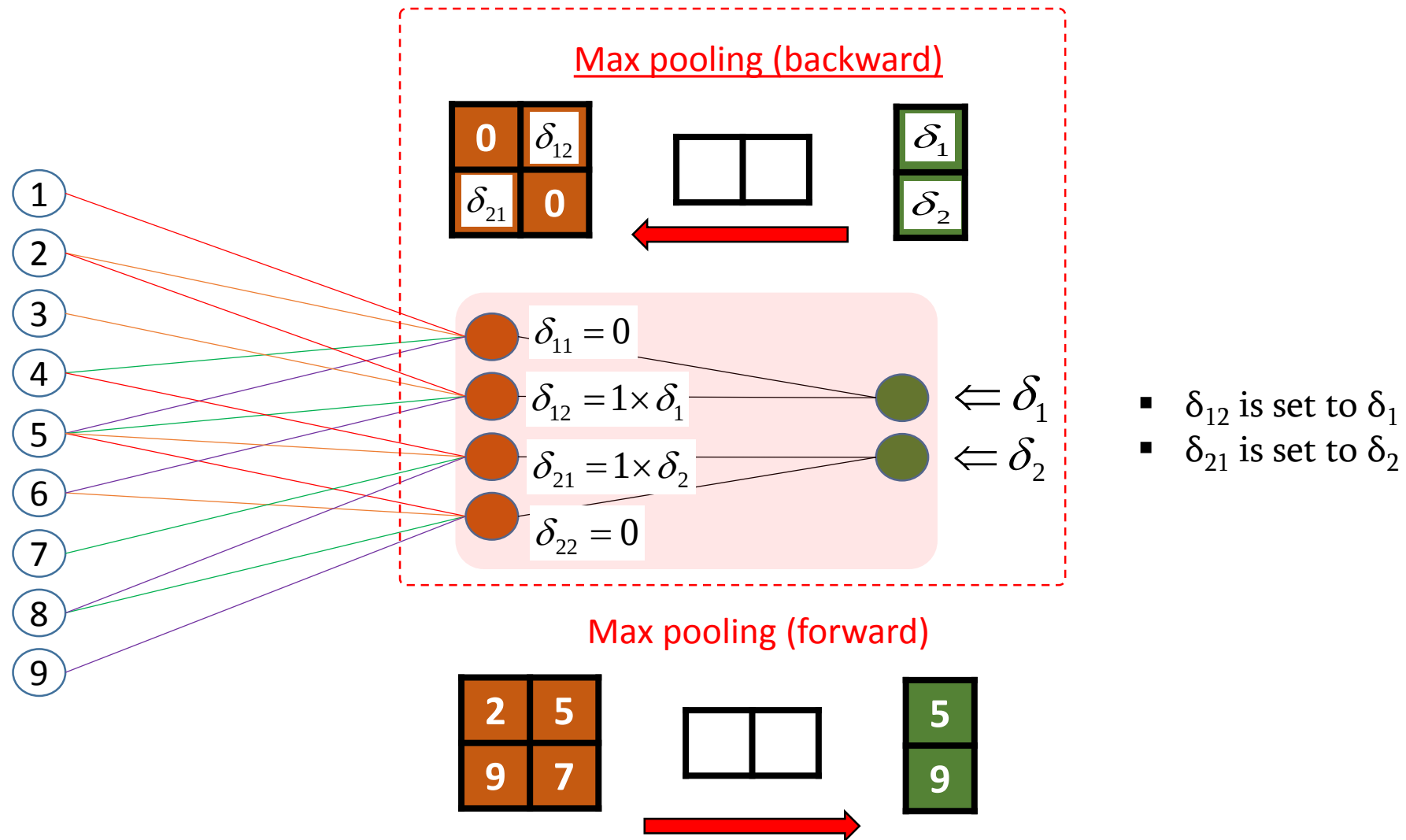
Pool

Fully Connected

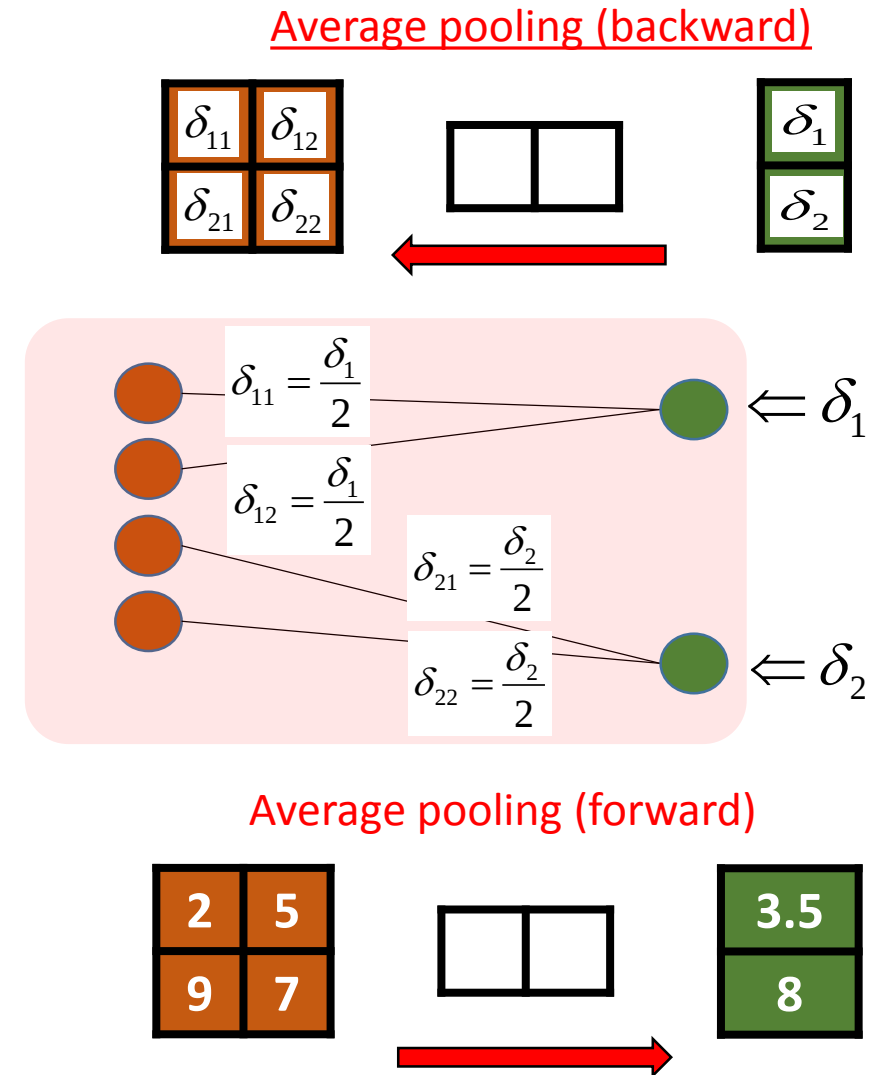
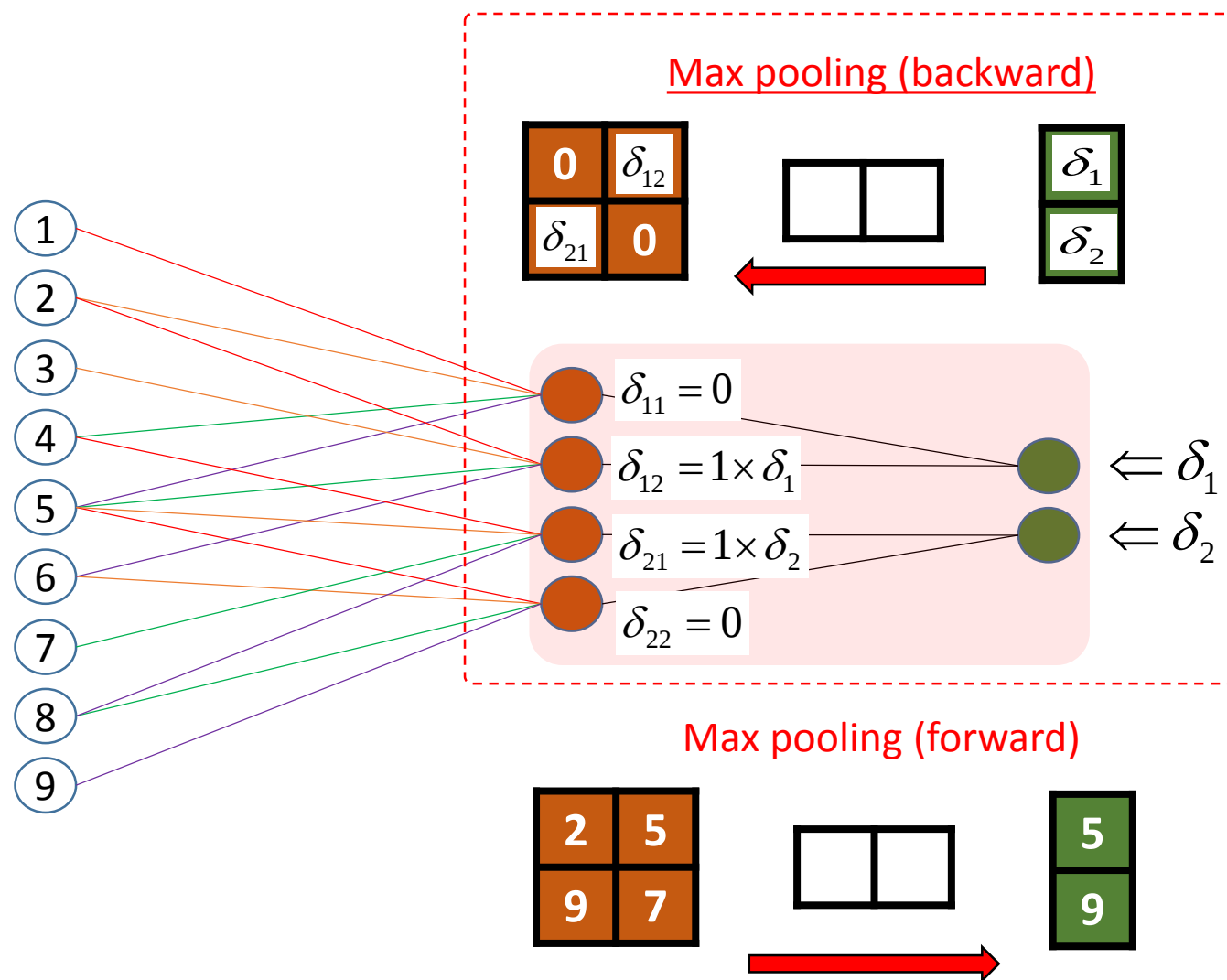
Backpropagation: Fully Connected Layer



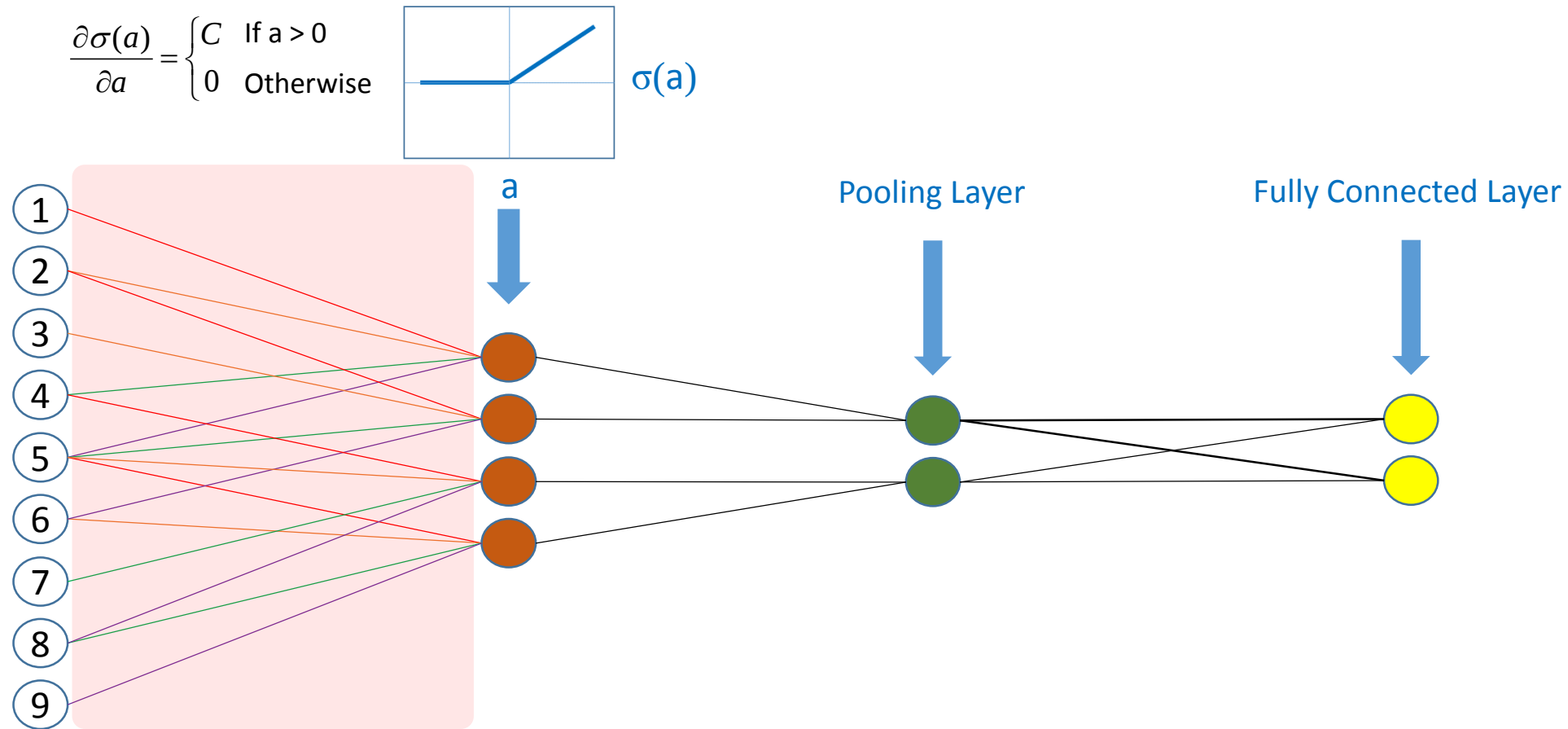
Backpropagation: Pooling Layer (Max pooling)



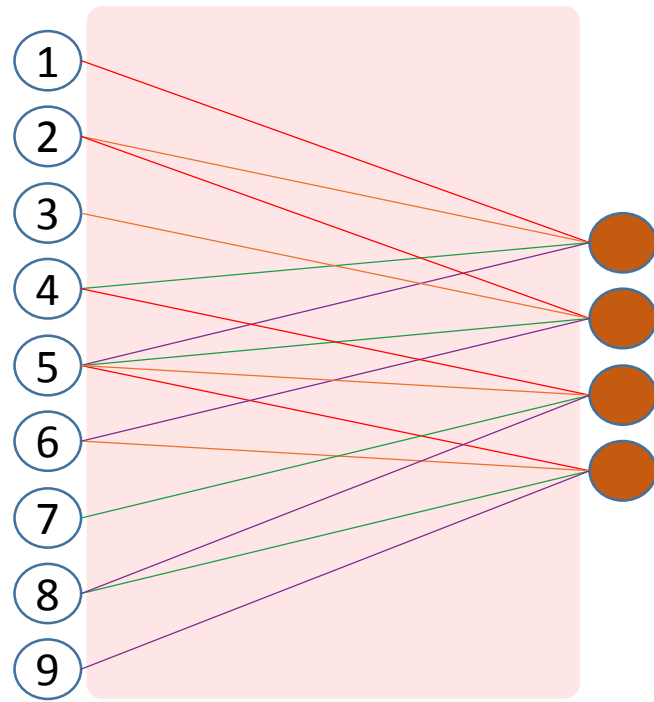
Backpropagation: Pooling Layer (Average pooling)



Backpropagation: Convolution Layer



Backpropagation: Convolution Layer

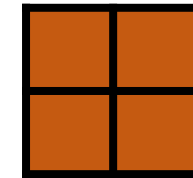


x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

Input

w_{11}	w_{12}
w_{21}	w_{22}

Kernel



Output

Backpropagation: Convolution Layer

□ Convolution

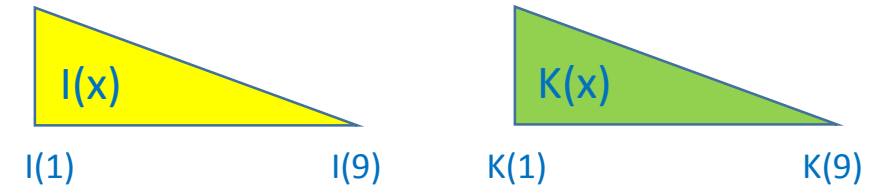
$$(I * K)_{ij} = \sum_{m=0} \sum_{n=0} I(m, n) K(i - m, j - n)$$

Individual elements in both functions, located in the **opposite index**, are multiplied and added.

□ Cross-correlation

$$(I \circ K)_{ij} = \sum_{m=0} \sum_{n=0} I(i + m, j + n) K(m, n)$$

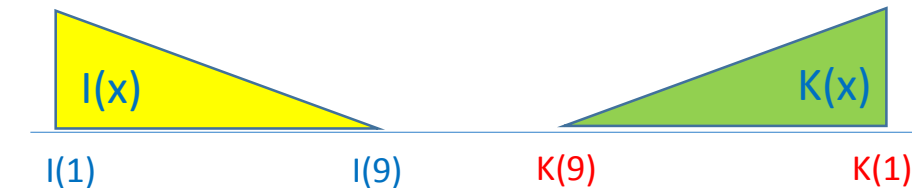
Individual elements in both functions, located in the **same index**, are multiplied and added.



□ Convolution



□ Cross-correlation



Convolution $(I * K)_{ij} = (I \circ \text{flip}(K))_{ij}$ Correlation

Backpropagation: Convolution Layer

❑ Convolution

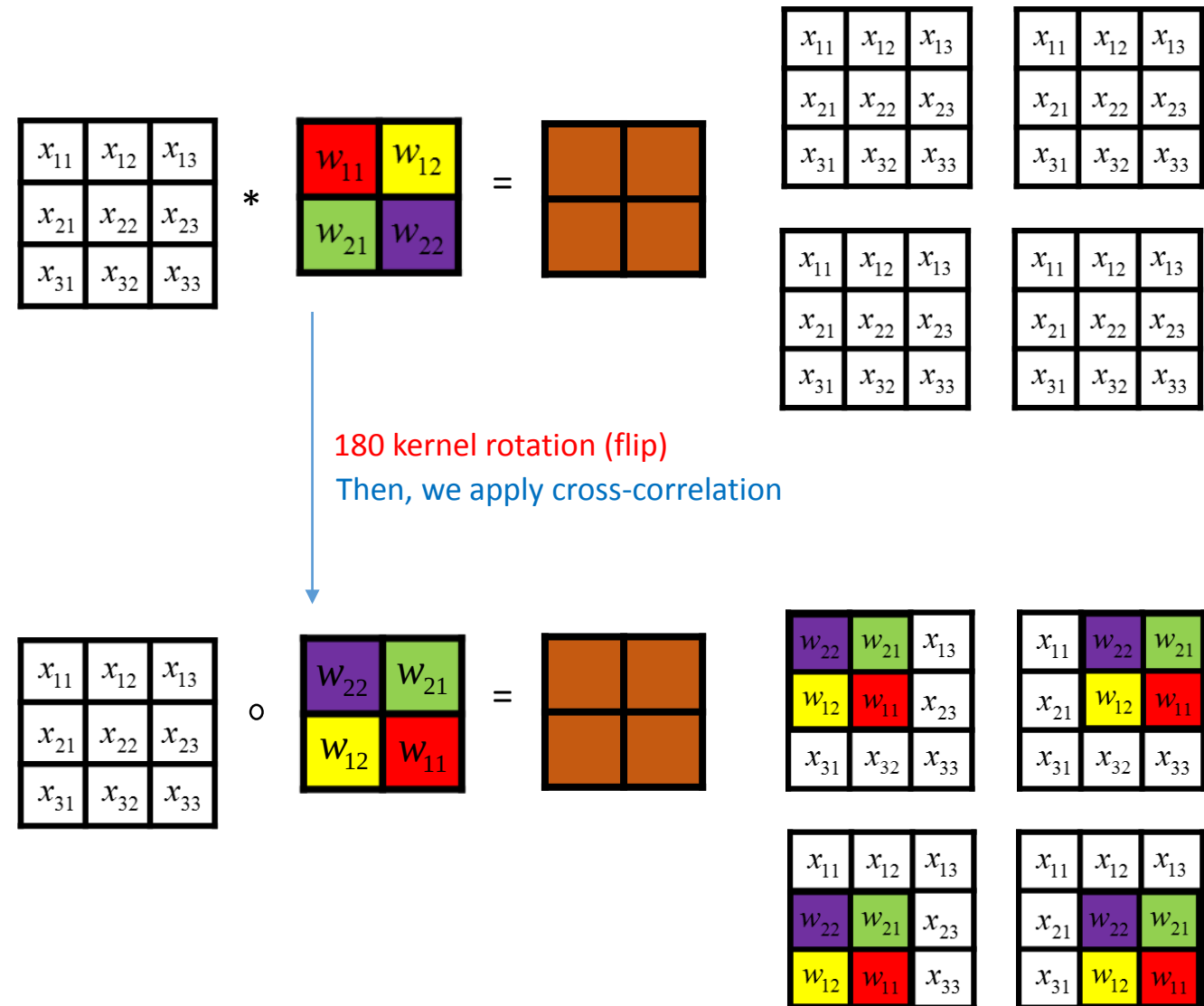
$$(I * K)_{ij} = \sum_{m=0} \sum_{n=0} I(m, n) K(i - m, j - n)$$

Individual elements in both functions, located in the **opposite index**, are multiplied and added.

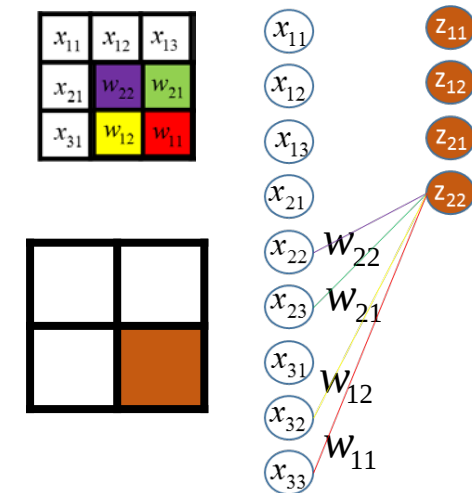
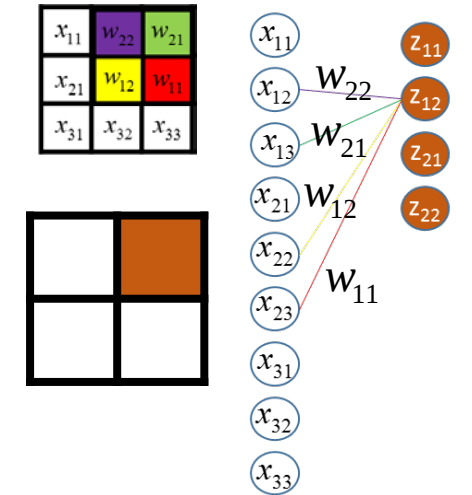
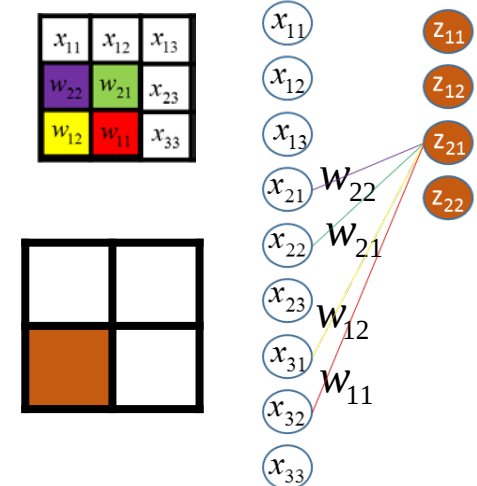
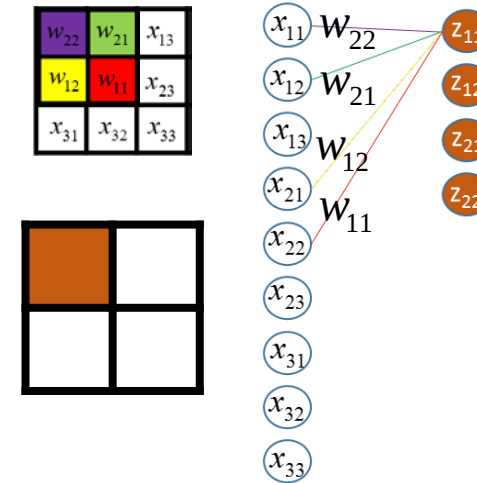
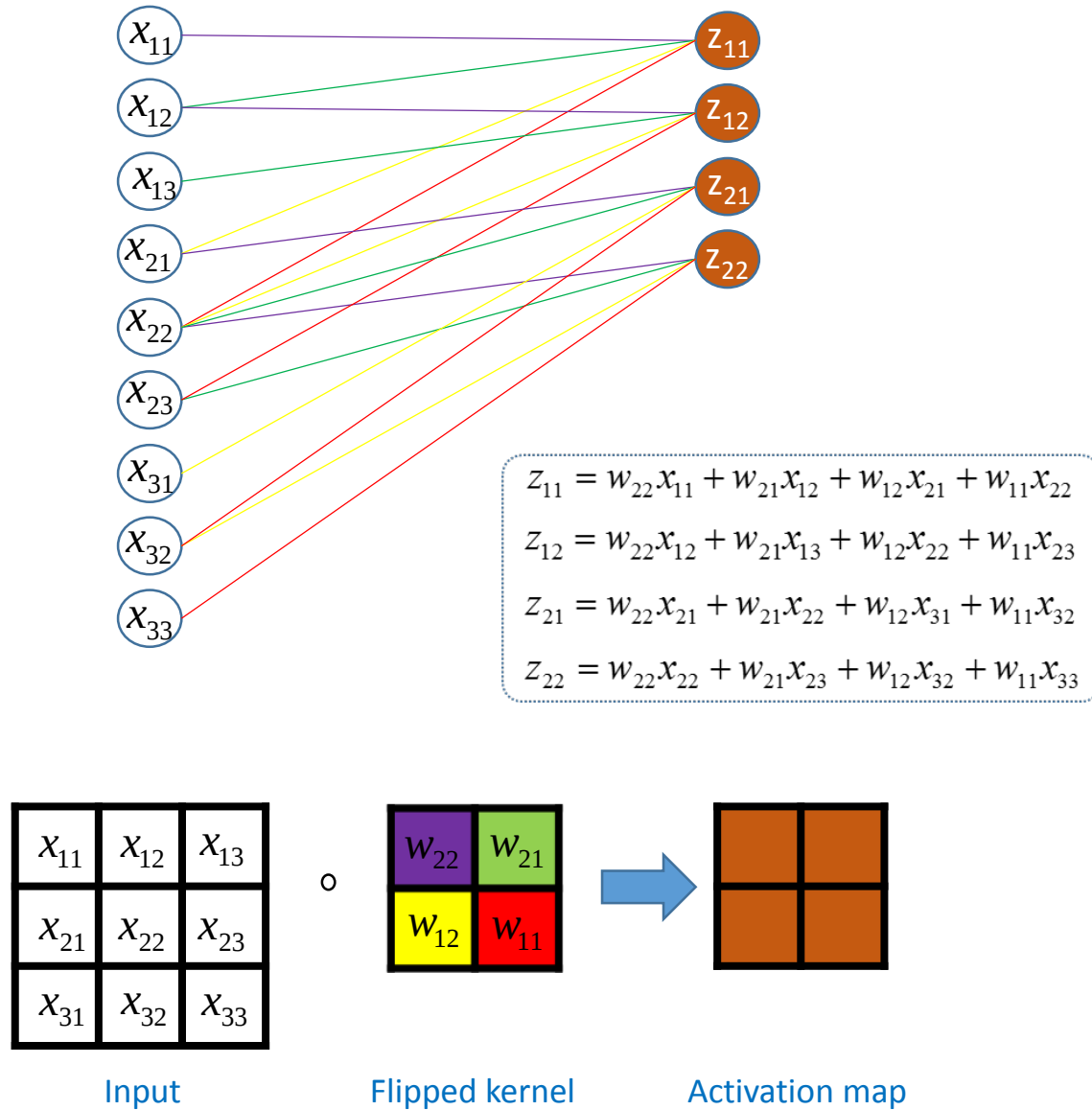
❑ Cross-correlation

$$(I \circ K)_{ij} = \sum_{m=0} \sum_{n=0} I(i + m, j + n) K(m, n)$$

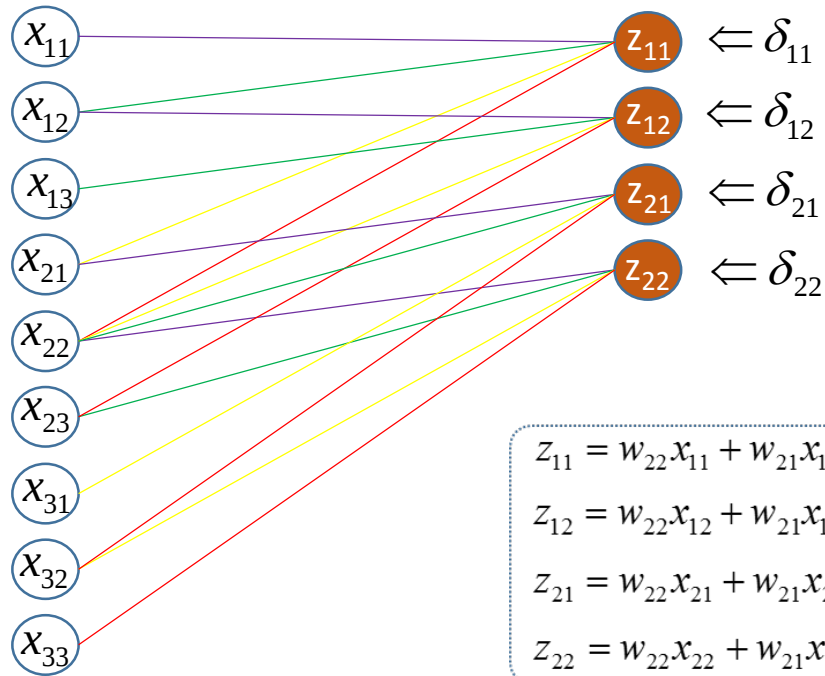
Individual elements in both functions, located in the **same index**, are multiplied and added.



Backpropagation: Convolution Layer - forwarding



Backpropagation: Convolution Layer – backward: correlation between "w" and "δ"



$$\begin{aligned} z_{11} &= w_{22}x_{11} + w_{21}x_{12} + w_{12}x_{21} + w_{11}x_{22} \\ z_{12} &= w_{22}x_{12} + w_{21}x_{13} + w_{12}x_{22} + w_{11}x_{23} \\ z_{21} &= w_{22}x_{21} + w_{21}x_{22} + w_{12}x_{31} + w_{11}x_{32} \\ z_{22} &= w_{22}x_{22} + w_{21}x_{23} + w_{12}x_{32} + w_{11}x_{33} \end{aligned}$$

x_{11}	x_{12}	x_{13}
x_{21}	x_{22}	x_{23}
x_{31}	x_{32}	x_{33}

Input

o

δ_{11}	δ_{12}
δ_{21}	δ_{22}

Activation map



w_{22}	w_{21}
w_{12}	w_{11}

kernel

$$(1) \frac{\partial E}{\partial w_{mn}} = \sum_{i=1}^{N-F+1} \sum_{j=1}^{N-F+1} \delta_{ij} \frac{\partial z_{ij}}{\partial w_{mn}}$$

$$\frac{\partial E}{\partial w_{11}} = \delta_{11}x_{22} + \delta_{12}x_{23} + \delta_{21}x_{32} + \delta_{22}x_{33}$$

$$\frac{\partial E}{\partial w_{12}} = \delta_{11}x_{21} + \delta_{12}x_{22} + \delta_{21}x_{31} + \delta_{22}x_{32}$$

$$\frac{\partial E}{\partial w_{21}} = \delta_{11}x_{12} + \delta_{12}x_{13} + \delta_{21}x_{22} + \delta_{22}x_{23}$$

$$\frac{\partial E}{\partial w_{22}} = \delta_{11}x_{11} + \delta_{12}x_{12} + \delta_{21}x_{21} + \delta_{22}x_{22}$$

δ_{11}	δ_{12}	x_{13}
δ_{21}	δ_{22}	x_{23}
x_{31}	x_{32}	x_{33}

x_{11}	δ_{11}	δ_{12}
x_{21}	δ_{21}	δ_{22}
x_{31}	x_{32}	x_{33}

w_{22}	w_{21}
w_{12}	w_{11}

x_{11}	x_{12}	x_{13}
δ_{11}	δ_{12}	x_{23}
δ_{21}	δ_{22}	x_{33}

x_{11}	x_{12}	x_{13}
x_{21}	δ_{11}	δ_{12}
x_{31}	δ_{21}	δ_{22}

Backup Slides

Backpropagation: Convolution Layer – backward: why correlation here - proof?

$$(1) \frac{\partial E}{\partial w_{mn}} = \sum_{i=1}^{N-F+1} \sum_{j=1}^{N-F+1} \delta_{ij} \frac{\partial z_{ij}}{\partial w_{mn}}$$

One in the right side was obtained using convolution previously.

$$= \sum_{i=1}^{N-F+1} \sum_{j=1}^{N-F+1} \delta_{ij} \frac{\partial}{\partial w_{mn}} \left(\sum_k \sum_q w_{kq} x_{i+k, j+q} \right)$$

$$\begin{aligned} z_{11} &= w_{22}x_{11} + w_{21}x_{12} + w_{12}x_{21} + w_{11}x_{22} \\ z_{12} &= w_{22}x_{12} + w_{21}x_{13} + w_{12}x_{22} + w_{11}x_{23} \\ z_{21} &= w_{22}x_{21} + w_{21}x_{22} + w_{12}x_{31} + w_{11}x_{32} \\ z_{22} &= w_{22}x_{22} + w_{21}x_{23} + w_{12}x_{32} + w_{11}x_{33} \end{aligned}$$

We only consider when “ $w_{mn} = w_{kq}$ ”, in other words “ $m=k, n=q$ ”.

$$= \sum_{i=1}^{N-F+1} \sum_{j=1}^{N-F+1} \delta_{ij} \frac{\partial}{\partial w_{mn}} \left(\sum_k \sum_q w_{mn} x_{i+m, j+n} \right)$$

$$= \sum_{i=1}^{N-F+1} \sum_{j=1}^{N-F+1} \delta_{ij} x_{m+i, n+j}$$

It is correlation

Finally, “ ∂w ” is the result of cross correlation between “ x ” and “ δ ” previously.

